

A Structural Design Comparison Between Two Reinforced Concrete Regular 6-Level Buildings using Soil-Structure Interaction in Linear Range

Comparación de diseño estructural entre dos edificaciones de concreto armado de seis niveles utilizando interacción suelo-estructura en el rango lineal

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ABSTRACT

Structural engineers commonly design superstructures as fixed at the base and transmit the reactions to the infrastructure in order to design the foundation system and estimate the displacement of the soil while disregarding the change in seismic response that this induces. In this article, the foundation system was transformed into equivalent springs, and the seismic response in the linear range was compared and quantified, obtaining results such as increased periods, increased amounts of steel reinforcement in beams (between 7% and 25%) and columns (between 29% and 39%), an increase in the number of stirrups per linear meter (between 3% and 11% in columns and between 5% and 45% in beams) and drifts (between 1% and 14%), and a decrease in basal shear (up to 20%), which directly affects the design of the structure. This study concludes that the inclusion of the soil-structure interaction is necessary for structural design in the linear range.

Keywords: seismic response, foundation system, soil-structure interaction, linear range

RESUMEN

Comúnmente, los ingenieros estructurales diseñan superestructuras como empotradas en la base y transmiten las reacciones a la infraestructura para diseñar el sistema de cimientos y estimar los desplazamientos del suelo, obviando el cambio en la respuesta sísmica que esto induce. En este artículo se transformó el sistema de cimientos en resortes equivalentes y se comparó y cuantificó la respuesta sísmica en el rango lineal, obteniendo resultados como aumento de los períodos, aumento de las cuantías de acero de refuerzo en vigas (entre 7% y 25%) y columnas (entre 29% y 39%) y las derivas (entre 1% y 14%), y una disminución de cortantes basales (hasta 20%), lo que afecta de forma directa el diseño de la estructura. Este estudio concluye que es necesaria la inclusión de la interacción suelo estructura en el diseño estructural en el rango lineal.

Palabras clave: respuesta sísmica, sistema de cimientos, interacción suelo-estructura, rango lineal

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Introduction

Structural engineering always aims for the best way to represent a real structure in a mathematical model in order to obtain the best approach to the reality. Soil-structure interaction is one of many ways to get closer to the behavior of a real structure. There are many ways to represent this relationship: it could be static or dynamic, linear or non-linear, and the possible combinations among them (Zeevaert, 1980; Mejía-Bermejo, 2017; Hernández-Velasco, 2013; Galicia and León, 2007; Villareal, G. 2009). To represent soil and substructure displacements, it is necessary to calculate the foundation system, in order to substitute it with equivalent springs using the concepts of rotational and translational stiffness (Uribe-Escamilla, 2000; Weaver and Gere, 1990; López *et al.*, 2019), which express that a structural element can be represented through its rotational and translational stiffness coefficients, as shown in Equations (1) and (2).

$$F = K_T d \quad (1)$$

$$F = K_R \theta \quad (2)$$

where F is the force applied on a structural element; K_T is the element's translational stiffness constant; d is the displacement in the force's direction; M is the torsional or bending moment applied on the structural element; K_R is the element's rotational stiffness constant; and θ is the rotation in the moment's direction. To make soil-structure interaction possible, it is necessary to obtain the values of F , d , M , and θ . Thus, the values of K_T and K_R , can be calculated for each direction, representing the equivalent spring constants for the foundation system, as shown in Figure 1. It is worth noting that that K_T and $F = K_R$ remain linear, with a single value for each direction (Wu and Pantelides, 2019).

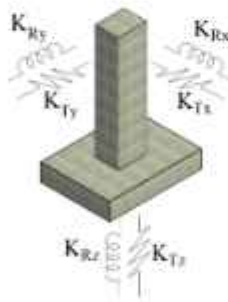


Figure 1. Equivalent springs for foundation system.
Source: (Castro-Pilco and Pérez-Martínez, 2020)

After calculating the equivalent springs, the initial structural model fixed at the base is submitted to a new structural analysis using springs (Figure 2), thus allowing changes in global stiffness and, hence, a variation in the results.

Methodology

This research was based on basic structural concepts for soil-structure interaction in linear range. The structure used for this research was residential and consisted of six levels, one elevator, one stair module, with 3 types of foundation soil and

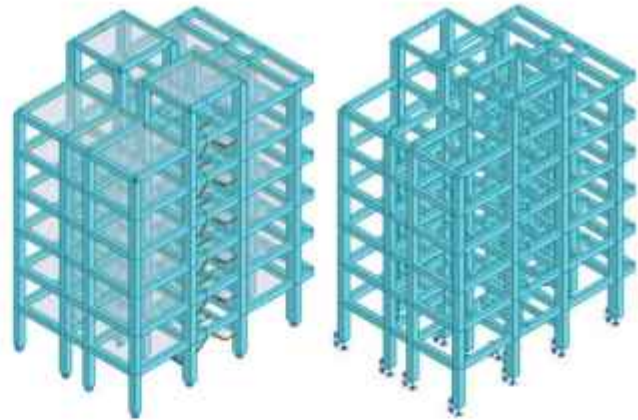


Figure 2. Structural model with fixed supports (left) and equivalent springs (right) at the base.
Source: (Authors)

spectral parameters typical from Quito, Ecuador. The main objective of this research was to quantify the differences in seismic response and structural members design of the same regular reinforced concrete structure using soil-structure interaction in linear range. Basic structural dynamics applied to building analysis and design explains how to obtain the main structural criteria in order to accept or reject the structural member cross section, with the vibrational modes, periods, and drifts being the most important, including the force diagrams for structural member design. Based on the basic concepts of structural dynamics, the modal matrix and the structure's frequencies can be calculated from Equations (3), (4), and (5).

$$[M] \{\ddot{x}\} + [C] \{\dot{x}\} + [Ke] \{x\} = 0 \quad (3)$$

$$\phi = \text{eigenvectors} [[Ke], [M]] \quad (4)$$

$$w^2 = \text{eigenvalues} [[Ke], [M]] \quad (5)$$

where $[Ke]$ is the structure's equivalent stiffness matrix, which depends on the cross section, inertia, length, supports, and material of each structural member for 2D planar analysis; $[M]$ is the mass matrix of the structure; $[C]$ is the matrix of damping factor, which is considered to be constant in this research; $\ddot{x}$ is the structure acceleration vector; $\dot{x}$ is the structure velocity vector; x is the structure displacement vector; ϕ is the modal matrix; and w is the angular velocity for each vibrational mode.

In this research, three different inelastic spectra were considered, and the general solution was obtained by performing modal-spectral analysis, with modal truncation for three vibration modes per floor, and then obtaining the response of each degree of freedom (DOF) by applying Equations (6) and (7).

$$\ddot{D}_n + 2\zeta_n w_n \dot{D}_n + w_n^2 D_n = \ddot{u}_g \quad (6)$$

$$u_n = \frac{\phi_n^T M t}{m_n} \phi_n D_n \quad (7)$$

where ζ_n is the damping value per mode; w_n is the angular velocity per mode; D_n is the modal displacement value per

mode; $\ddot{u}_g$ is the spectral acceleration; i is the directional vector for the spectral acceleration (x , y , z); u_n is the displacement for each DOF and each vibrational mode; m is the modal mass; and n is the number of each vibrational mode. The total response is estimated through the CQC method. These calculations were made with Autodesk Robot Structural 2020, academic version (547L1, 900-95470127).

The $[K_e]$ factor is the key for the structural changes in results using soil-structure interaction due to the change in stiffness in the first level, which directly affects global stiffness. If a structure is assumed to be fixed at the base or uses equivalent springs, stiffness changes according to the case. The fixed element has translational and rotational restrictions at the base, whereas the non-fixed element has no restrictions, thus allowing displacements and rotations at the base and increasing displacements. According to the literature (Falconfi, 2008; Chopra, 1980; Reyes, 1998; Paz, 1992), stiffness decreases are in accordance with equivalent stiffness theory, which expresses an equivalence with the configuration through Equation (8), for springs in parallel arrangement, and Equation (9), for springs in continuous arrangement.

$$K_e = \sum_{i=1}^n K \quad (8)$$

$$\frac{1}{K_e} = \sum_{i=1}^n \frac{1}{K_n} \quad (9)$$

The stiffness modification at the base directly affects the $[K_e]$ structure matrix, modifying the periods, frequency, modal response, and modal displacements. Some studies express that damping is another important factor (Lutes and Sarkani, 1995; Cruz, and Miranda, 2017). However, this value has remained constant, imposing a 5,00% damping value corresponding to structures provided with reinforced concrete.

Analysis and discussion

Inelastic design spectrum

This research was based on three typical soil types from the city of Quito, Ecuador, with an acceleration value on rock according to a seismic hazard of 0,40 g. The three soil types were A, C, and E, based on the scale from A to E, with A being the best soil type, with a shear wave velocity greater than 1500,00 m/s; C, an intermediate soil, with shear wave velocities between 360 m/s and 760 m/s; and E, the worst soil type, with a shear wave velocity of less than 180 m/s. The inelastic spectrum by soil type used for the analysis are shown in Figure 3, as a fraction of gravity according to the Ecuadorian building regulations for seismic hazard (NEC, 2014).

Fixed superstructure analysis and design

The first step in the analysis is the correct design of the structure, in accordance with the regulations (ACI, 2014 2019; NEC, 2015; ASCE/FEMA, 2000), aiming to guarantee a

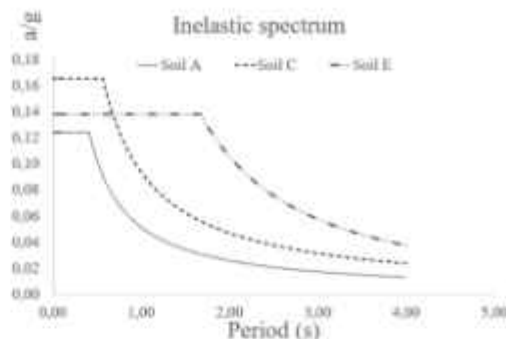


Figure 3. Inelastic seismic design spectrum for each soil type.
Source: Authors

good capacity, stiffness, and seismic response. Vibrational modes and displacements (mm) for the three main periods are shown in Figures 4, 5, and 6 for modal analysis with fixed structure. Note that these displacements are the result of the application of Equations (6) and (7) for each DOF and for each vibrational mode.

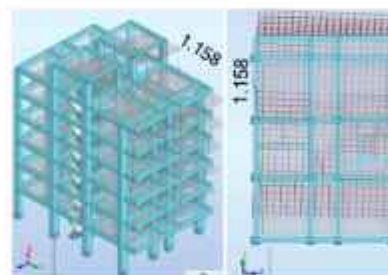


Figure 4. First vibrational mode (period 0,78 s).
Source: Authors

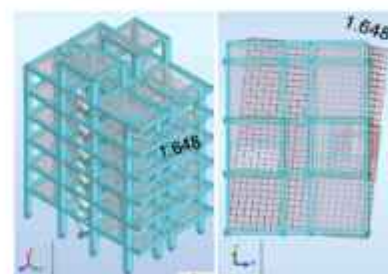


Figure 5. Second vibrational mode (period 0,65 s).
Source: Authors

Substructure analysis and design

Following the traditional procedure, reactions from the superstructure are turned into actions on the substructure, in order to analyze and design the foundation system for the three soil types. The sizes of the foundations have been selected so as not to exceed the allowable stresses at the foundation level, which are represented in Figures 10 and 11 by soil type. The influence of the foundation system was checked, concluding that there was no considerable difference in stress and displacements. The foundation system was analyzed

using equivalent springs for vertical displacements at the base to simulate soil elasticity (Figure 7), based on Ballast coefficient (Meli Piralla, 1986). The equivalent soil stiffness is shown in Table 1, using a finite element node spacing of 25 cm (de Macedo Wahrhaftig, 2020) (Figures 8 and 9).

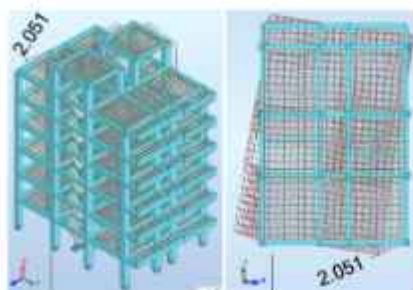


Figure 6. Third vibrational mode (period 0,58 s).

Source: Authors

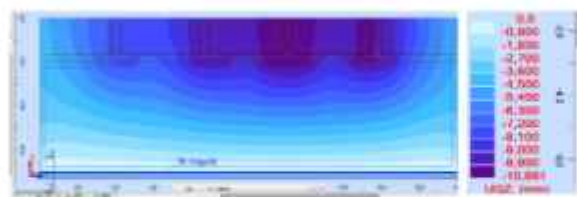


Figure 7. Isolines for displacements.

Source: Authors

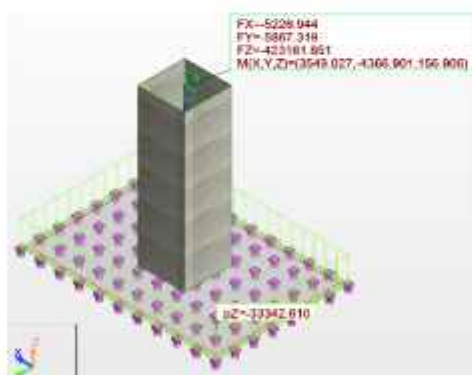


Figure 8. Foundation system using equivalent springs at the isolated foundation base (kN, kN.m).

Source: Authors

Table 1. Ballast coefficient for each soil type

Soil type	Ballast Coefficient (N/cm ³)	Equivalent stiffness (N/cm)
A	470,88	294 300,00
B	196,20	122 625,00
C	78,48	49 050,00

Source: Authors

The definitive dimensions for each foundation system and for each soil type are shown in Figures 10 and 11, according to (Pérez-Valcárcel, J., 2013; Garza-Vásquez, 2000; Paz, 1992).

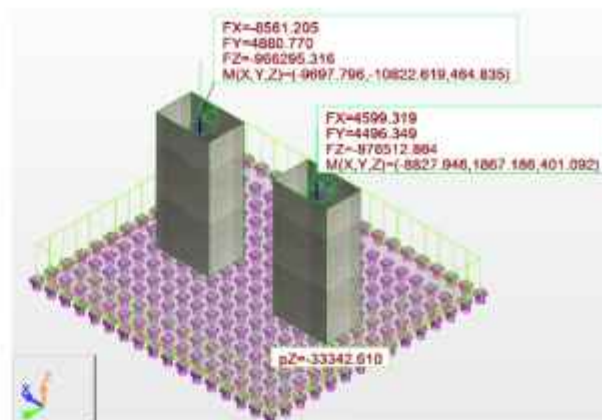


Figure 9. Foundation system using equivalent springs at the combined foundation base (kN, kN.m).

Source: Authors

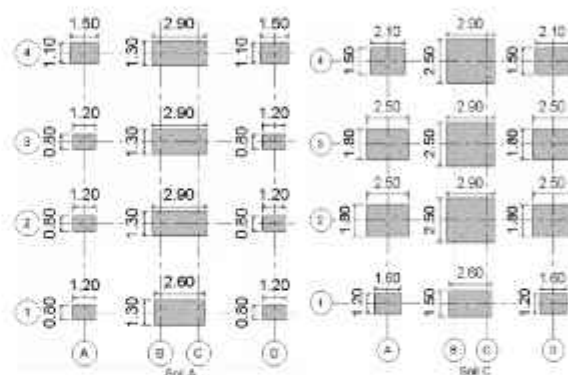


Figure 10. Foundation system for soils A and C (m).

Source: Authors

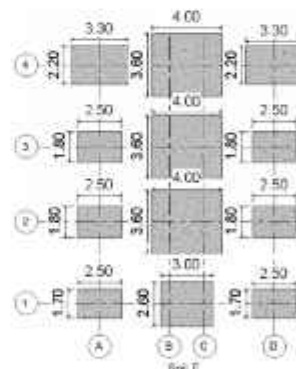


Figure 11. Foundation system for soil E (m).

Source: Authors

According to Equations (1) and (2), stiffness constants for each soil type are shown in Tables 2 to 7. After calculating the equivalent spring constants, the fixed supports were replaced, thus changing structure stiffness. Please note that, on average, stiffness decreases for soils A to E, with soil A being the best, and E the worst in terms of behavior.

Table 2. Equivalent translational springs constant for soil A

		Translational stiffness (MN/m)			
Axis		4	3	2	1
A	kx	164,41	127,78	126,47	56,81
A	ky	50,99	21,72	59,45	63,80
A	kz	1 030,00	1 442,00	1 442,00	765,19
B	kx	242,20	122,52	131,38	49,58
B	ky	56,22	30,46	59,48	62,03
B	kz	1 177,00	1 177,00	1 177,00	1 000,00
C	kx	158,67	124,10	126,78	62,73
C	ky	55,48	58,61	52,50	63,09
C	kz	1 177,00	1 177,00	1 177,00	1 000,00
D	kx	202,59	134,92	125,81	50,78
D	ky	54,24	72,36	41,95	84,62
D	kz	1 030,00	1 442,00	1 442,00	765,15

Source: Authors

Table 3. Equivalent rotational springs constant for soil A

		Rotational stiffness (MN.m/rad)			
Axis		4	3	2	1
A	kx	393,65	243,77	247,05	94,97
A	ky	233,22	267,74	169,1	77,18
A	kz	5,40E-4	6,40E-4	8,30E-5	1,50E-4
B	kx	196,61	254,29	247,51	113,36
B	ky	220,77	250,66	169,24	81,66
B	kz	9,50E-05	2,70E-4	2,40E-5	7,80E-5
C	kx	400,97	260,23	245,77	76,69
C	ky	220,48	173,36	189,31	77,78
C	kz	2,80E-04	5,60E-4	1,60E-4	3,80E-5
D	kx	287,98	224,1	248,88	111,68
D	ky	224,77	134,98	216,23	18,68
D	kz	2,20E-4	1,80E-3	8,80E-4	5,00E-4

Source: Authors

Table 4. Equivalent rotational springs constant for soil C

		Rotational stiffness (MN.m/rad)			
Axis		4	3	2	1
A	kx	462,38	243,77	247,05	94,97
A	ky	247,21	267,74	169,1	77,18
A	kz	4,90E-4	6,40E-4	8,30E-5	1,50E-4
B	kx	196,61	254,29	247,51	113,36
B	ky	220,77	250,66	169,24	81,66
B	kz	9,50E-5	2,70E-4	2,40E-5	7,80E-5
C	kx	400,97	260,23	245,77	76,69
C	ky	220,48	173,36	189,31	77,78
C	kz	2,80E-4	5,60E-4	1,60E-4	3,80E-4
D	kx	341,03	224,1	248,88	111,68
D	ky	237,49	134,98	216,23	18,68
D	kz	1,90E-4	1,80E-3	8,80E-4	5,00E-4

Source: Authors

Analysis and design of the superstructure using equivalent springs

As shown in Figure 2, the fixed supports were replaced, and a new modal analysis including the new global stiffness was made. The first main comparison takes place on displacements and periods, as shown in Figures 12 to 14. Periods and displacements remained closer with the use of equivalent springs, and they were located at different points of the

Table 5. Equivalent translational springs constant for soil C

		Translational stiffness (MN/m)			
Axis		4	3	2	1
A	kx	193,12	127,78	126,47	56,81
A	ky	54,05	21,72	59,45	63,8
A	kz	772,52	1 079,13	1 078	527,32
B	kx	242,2	122,52	131,38	49,58
B	ky	56,22	30,46	59,48	62,03
B	kz	876,72	876,77	876,81	472,11
C	kx	158,67	124,1	126,78	62,73
C	ky	55,48	58,61	52,5	63,09
C	kz	876,72	876,77	876,81	472,11
D	kx	239,91	134,92	125,81	50,78
D	ky	57,31	72,36	41,95	84,62
D	kz	772,54	1 079,10	1 079,00	527,34

Source: Authors

Table 6. Equivalent translational springs constant for soil E

		Translational stiffness (MN/m)			
Axis		4	3	2	1
A	kx	164,41	127,78	126,47	56,81
A	ky	50,99	21,72	59,45	63,8
A	kz	1 030,00	1 442,00	1 442,00	765,19
B	kx	242,2	122,52	131,38	49,58
B	ky	56,22	30,46	59,48	62,03
B	kz	1 177,00	1 177,00	1 177,00	1 000,00
C	kx	158,67	124,1	126,78	62,73
C	ky	55,48	58,61	52,5	63,09
C	kz	1 177,00	1 177,00	1 177,00	1 000,00
D	kx	202,59	134,92	125,81	50,78
D	ky	54,24	72,36	41,95	84,62
D	kz	1 030,00	1 442,00	1 442,00	765,15

Source: Authors

Table 7. Equivalent rotational springs constant for soil E

		Rotational stiffness (MN.m/rad)			
Axis		4	3	2	1
A	kx	393,65	243,77	247,05	94,97
A	ky	233,22	267,74	169,1	77,18
A	kz	5,40E-4	6,40E-4	8,30E-5	1,50E-4
B	kx	196,61	254,29	247,51	113,36
B	ky	220,77	250,66	169,24	81,66
B	kz	9,50E-5	2,70E-4	2,40E-5	7,80E-5
C	kx	400,97	260,23	245,77	76,69
C	ky	220,48	173,36	189,31	77,78
C	kz	2,80E-4	5,60E-4	1,60E-4	3,80E-5
D	kx	287,98	224,1	248,88	111,68
D	ky	224,77	134,98	216,23	18,68
D	kz	2,20E-4	1,80E-3	8,80E-4	5,00E-4

Source: Authors

structure, in comparison with Figures 4 to 6, which means that foundation equivalent system reflects a similar response. On the other hand, results for frequencies and periods are shown in Tables 8 and 9, and the maximum displacements are shown in table 10 for each soil type and the first three vibrational modes. The frequencies decrease while the periods increase, as well as the maximum displacements. Additionally, the global stiffness estimate is shown in Table 11, which

decreases from soil E to soil A, meaning that the stiffness is not related only to the size of the foundation system, but also to the Ballast coefficient and the type of foundation (isolated or combined).



Figure 12. Maximum displacements for soil A (cm): 1st mode on the left, 2nd mode in the middle, and 3rd mode on the right.

Source: Authors

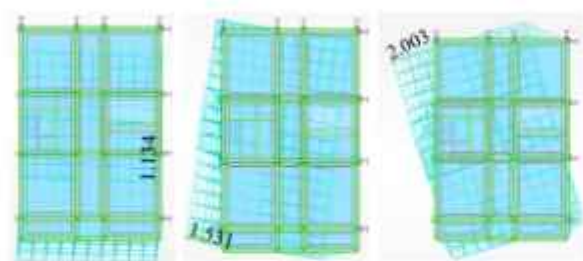


Figure 13. Maximum displacements for soil C (cm): the 1st mode on the left, the 2nd mode in the middle, and the 3rd mode on the right.

Source: Authors



Figure 14. Maximum displacements for soil E (cm): 1st mode on the left, the 2nd mode in the middle, and the 3rd mode on the right.

Source: Authors

Table 8. Frequencies

Mode	Frequencies w (rad/s)			
	Fixed	Springs (A)	Springs (C)	Springs (E)
1	1,27	1,19	1,18	1,17
2	1,54	1,44	1,42	1,41
3	1,73	1,60	1,59	1,58

Source: Authors

Comparisson between fixed models and with springs models

To compare the structural response among the fixed and non-fixed models, a complete design for each soil type was made. The final dimensions for the fixed structure remained the same for the non-fixed structure, in order to compare them against

Table 9. Periods

Mode	Periods T (s)			
	Fixed	Springs (A)	Springs (C)	Springs (E)
1	0,78	0,84	0,85	0,85
2	0,65	0,70	0,70	0,71
3	0,58	0,62	0,63	0,63

Source: Authors

Table 10. Maximum displacements

Maximum displacements (cm)			
Fixed	Springs (A)	Springs (C)	Springs (E)
1,158	1,131	1,134	1,137
1,648	1,565	1,531	1,510
2,051	2,002	2,003	2,002

Source: Authors

Table 11. Global stiffness

	K_x (kN/mm)	K_y (kN/mm)	K average (kN/mm)
Fixed	166,69	126,38	146,53
A	129,06	123,17	126,12
C	137,56	100,11	118,83
E	133,79	98,65	116,22

Source: Authors

the reinforcement steel areas and drifts. Reinforcement steel areas for beams and columns for each model are shown in Tables 12 to 16. It can be observed that, for soil A, the required reinforcement increase is related to the stiffness, which is the highest among the three soil types, approaching to fixed model (Wahrhaftig and Brasil, 2017).

Table 12. Average required reinforcement

Soil type	Average required reinforcement (cm ²)				Average required reinforcement (%)	
	Fixed		Equivalent springs		Difference	
	A_s^-	A_s^+	A_s^-	A_s^+	A_s^-	A_s^+
A	3,98	2,61	4,37	3,24	9,89	24,04
C	4,74	2,90	4,97	3,18	4,75	9,97
E	4,78	2,87	5,12	3,15	7,05	9,79

Source: Authors

Table 13. Total required reinforcement for beams (entire structure)

Soil type	Total required reinforcement for beams (cm ²)			
	Fixed		Equivalent springs	
	A_s^-	A_s^+	A_s^-	A_s^+
A	3 128,23	2 050,05	3 437,65	2 542,90
C	3 725,82	2 275,83	3 902,86	2 502,73
E	3 759,05	2 256,32	4 024,00	2 477,18

Source: Authors

The increase in positive and negative reinforcement areas implies an increase in the maximum deflection of beams, as shown in Table 17. Please note that these increases were negligible, but, if a structural design is susceptible

Table 14. Differences on total required reinforcement for beams (entire structure)

Soil type	Difference (cm ²)		Difference (%)	
	As-	As+	As-	As+
A	309,42	492,85	9,89	24,04
C	177,04	226,90	4,75	9,97
E	264,95	220,86	7,05	9,79

Source: Authors

Table 15. Total reinforcement required for columns (entire structure)

Soil type	Average required reinforcement (cm ²)		Total required reinforcement for columns (cm ²)	
	Fixed	Equivalent springs	Fixed	Equivalent springs
A	16,92	23,54	1 760,00	2 448,51
C	18,12	23,54	1 884,86	2 448,50
E	17,30	23,54	1 799,25	2 448,37

Source: Authors

Table 16. Differences on total reinforcement required for columns (entire structure)

Soil type	Difference (cm ²)	Difference (%)
A	688,51	39,12
C	563,64	29,90
E	649,12	36,08

Source: Authors

to deflections, the amplification must be considered, even though the increases for positive bending moments are being countered by the increase in negative bending moments, thus compensating the deflection increase. For columns, the quantities of reinforcement areas remain almost equal for each soil type, but, for all cases, there was a considerable increase associated with the new bending moments of the beams.

Table 17. Average maximum deflection for beams

Level	Average deflection (mm)			
	Fixed	A	C	E
1	-4,12	-4,20	-4,16	-4,21
2	-4,08	-4,05	-4,06	-4,12
3	-4,10	-4,08	-4,10	-4,13
4	-4,11	-4,10	-4,11	-4,14
5	-4,19	-4,16	-4,16	-4,19
6	-3,37	-3,37	-3,37	-3,46

Source: Authors

The direct relationship between bending moment and shear force implies an increase in shear effects; hence, a measurement of quantities of stirrups per length was established, as shown in Tables 19 and 20. Please note that stirrups quantities increase in average for beams and columns, and this is related to the increase bending moments due to gravitational effects and the reduction of the stiffness. Tables 21 and 22 show the base shear, and, for soil E, there is an amplification

Table 18. Average ratios for maximum deflection for beams

Level	Average ratios (spring/fixed)		
	A	C	E
1	1,0196	1,0103	1,0218
2	0,9919	0,9940	1,0087
3	0,9946	0,9998	1,0062
4	0,9991	1,0004	1,0066
5	0,9936	0,9943	1,0009
6	1,0002	1,0009	1,0272
Average	0,9998	0,9999	1,0119

Source: Authors

consistent with these results, whereas, for soils A and C, a reduction is observed while gravitational forces still increase.

Table 19. Stirrups per length in columns (16 mm)

Soil type	Fixed	Equivalent springs	Difference (%)
A	4,51	4,67	3,55
C	4,71	5,01	6,45
E	4,55	5,03	10,56

Source: Authors

Table 20. Stirrups per length in beams (10 mm)

Soil type	Fixed	Equivalent springs	Difference (%)
A	7,50	7,86	4,8
C	8,88	9,44	6,31
E	7,55	11,00	45,7

Source: Authors

As an example, the calculation of drifts for soil E are shown in Tables 21 and 22, while the total drifts and ratios for each soil type are shown in Table 23. Ratios were calculated using Equation (10). Elastic drifts were calculated according to (NEC, 2014), which specifies that, if $ratio > 1$, then drifts using equivalent springs are greater than drifts using fixed supports, and vice-versa.

$$ratio = \frac{\text{Equivalent springs drifts}}{\text{Fixed drifts}} \quad (10)$$

The procedure shown in Tables 21 and 22 was applied to all frames in both directions to obtain a global average for each structure (Table 23).

The results for drifts were as expected, which means that they were greater in models based on equivalent springs than in the fixed models. Although drifts for models with equivalent springs are greater, all models still remained within admissible values, which did not exceed the value of 0,02. Ratios increased from soil A to soil E, which is related to the global stiffness, modified due to the change from fixed supports to spring supports. Torsional irregularity was checked according to regulations and standards (FEMA, 2006, 2018; NEC, 2014), by applying Equation (8). If $r \geq 1,4$, then the torsional irregularity is extreme. If $1,2 \leq r \leq 1,4$, then the torsional

Table 21. Example for calculation of inelastic drifts for spectral Y displacements (soil E, one frame)

Level	Spectral (Y)				
	Fixed (mm)	Drifts	Equivalent springs (mm)	Drifts	Ratio
6	29,195	0,004	34,847	0,005	1,15
5	26,665	0,006	31,946	0,007	1,10
4	22,613	0,009	27,499	0,009	1,08
3	17,146	0,010	21,593	0,011	1,07
2	10,671	0,010	14,639	0,011	1,09
1	4,052	0,006	7,432	0,008	1,28
0	0,000	0,000	2,251	0,004	-
Average ratio Y					1,13

Source: Authors

Table 22. Example for calculation of inelastic drifts for spectral X displacements (soil E, one frame)

Level	Spectral (X)				
	Fixed (mm)	Drifts	Equivalent springs (mm)	Drifts	Ratio
6	15,662	0,002	17,594	0,003	1,19
5	14,177	0,004	15,825	0,004	1,09
4	11,923	0,005	13,369	0,005	1,04
3	9,006	0,005	10,324	0,005	1,02
2	5,617	0,005	6,855	0,005	1,01
1	2,170	0,003	3,365	0,003	1,02
0	0,000	0,000	1,159	0,002	-
Average ratio X					1,06

Source: Authors

Table 23. Average ratios for each soil type (all frames)

Soil type	Average ratios		
	Spectral X	Spectral Y	Average
A	1,04	0,98	1,01
C	1,04	1,01	1,02
E	1,16	1,12	1,14

Source: Authors

irregularity must be considered in the structural analysis and design by reinforcing columns or changing their configuration or orientation. If $r \leq 1,2$, then the torsional irregularity can be dismissed from the analysis. The results for torsional irregularity are shown in Tables 24 to 26.

Table 24. Average ratios for soil A (all frames)

Condition	Fixed		Equivalent springs	
	X	Y	X	Y
Displacements (mm)	14,17	13,25	14,58	14,96
	9,65	15,31	10,62	12,81
Average (mm)	11,91	14,28	12,60	13,88
r(mm/mm)	1,19	1,07	1,16	1,08

Source: Authors

Tables 24 to 26, show that torsional irregularity values remain admissible, and that the difference between fixed and equivalent

Table 25. Average ratios for soil C (all frames)

Condition	Fixed		Equivalent springs	
	X	Y	X	Y
Displacements (mm)	21,71	21,07	26,89	23,75
	17,94	24,96	18,81	27,70
Average (mm)	22,83	23,01	22,85	25,73
r (mm/mm)	1,21	1,08	1,18	1,08

Source: Authors

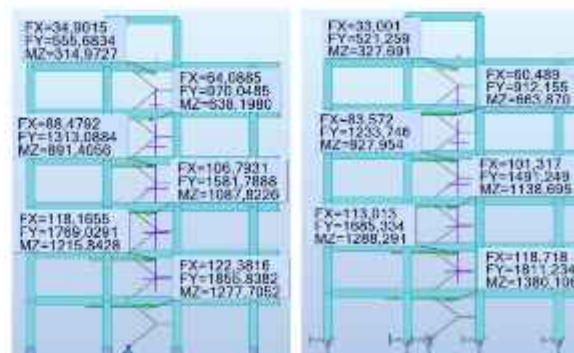
Table 26. Average ratios for soil E (all frames)

Condition	Fixed		Equivalent springs	
	X	Y	X	Y
Displacements (mm)	22,58	24,93	28,51	34,87
	14,22	28,92	18,13	29,88
Average (mm)	18,40	26,92	23,32	32,37
r (mm/mm)	1,23	1,07	1,22	1,08

Source: Authors

lent springs models remain closer. Despite using equivalent springs, the structure still has admissible values. Additionally, the ratios for torsional moments were evaluated. Therefore, if $ratio \geq 1$, then the torsional moment increases using equivalent springs and vice versa. The same equation was used to calculate ratio for base shear forces; Figure 15 shows the results for base shear forces and torsional moments for soil C.

Tables 27 to 29 show a decrease in shear forces in directions X and Y for soil A and C, although, for soil E, an increment is visible in the direction of the applied spectral forces. These results reflect that the displacements and rotations at the base using equivalent springs not only imply that the behavior of the structure changes for bad (in the form of drifts, reinforcement, or increasing torsional moments), but the spectral forces can also be reduced for each spectral load state. Table 30 shows similar results for torsional moments, decreasing for soils A and C, and increasing for soil E. These results can be attributed to the stiffness, given the fact that it decreased from soil A to E.

**Figure 15.** Base shear for soil C (kN, kN.m).

Source: Authors

Table 27. Soil A (spectral)

	X		Y	
Level	Base shear ratio			
	Fx	Fy	Fx	Fy
6	0,91	0,88	0,87	0,96
5	0,89	0,88	0,88	0,86
4	0,88	0,88	0,88	0,85
3	0,88	0,88	0,89	0,85
2	0,89	0,89	0,90	0,86
1	0,91	0,91	0,91	0,88
Average.	0,89	0,89	0,89	0,88

Source: Authors

Table 28. Soil C (spectral)

	X		Y	
Level	Base shear ratio			
	Fx	Fy	Fx	Fy
6	0,96	0,92	0,93	0,94
5	0,95	0,91	0,93	0,94
4	0,95	0,92	0,93	0,94
3	0,95	0,92	0,93	0,94
2	0,96	0,93	0,94	0,95
1	0,98	0,95	0,95	0,98
Average.	0,96	0,92	0,93	0,95

Source: Authors

Table 29. Soil E (spectral)

	X		Y	
Level	Base shear ratio			
	Fx	Fy	Fx	Fy
6	1,05	1,00	1,01	1,00
5	1,05	0,99	1,01	1,01
4	1,05	1,00	1,01	1,01
3	1,05	1,00	1,02	1,02
2	1,06	1,02	1,02	1,03
1	1,07	1,03	1,03	1,05
Average.	1,05	1,01	1,02	1,02

Source: Authors

Table 30. Ratios for torsional moments for each soil type

Level	Soil A		Soil C		Soil E	
	X	Y	X	Y	X	Y
Torsional Moment ratio (Mz)						
6	0,81	0,96	0,82	1,02	0,87	1,08
5	0,81	0,95	0,82	1,02	0,88	1,09
4	0,80	0,95	0,82	1,02	0,88	1,09
3	0,80	0,95	0,83	1,03	0,88	1,10
2	0,81	0,85	0,83	1,04	0,89	1,11
1	0,83	0,98	0,85	1,06	0,91	1,13
Av.	0,81	0,94	0,83	1,03	0,88	1,10

Source: Authors

Conclusions

According to the results, for this regular structure, soil-structure interaction in linear range has an impact on the analysis and design. The former is related with reinforcement areas for structural elements which increased for positive and

negative bending moments in all the structural models, while also increasing the quantities of stirrups per length.

Drift values showed an expected increase, being greater for soil E (14%), which was the most critical in terms of stiffness and soil resistance, as well as subjected to gravitational and seismic influences, thus allowing more displacements and rotations at the base. However, it could be enhanced by giving more stiffness to its foundation system by mechanically altering the soil properties to preserve the superstructure's cross section.

A similar response was obtained for torsional irregularity, but, in this case, it remained almost equal in terms of displacement, which is related with stiffness reduction and increasing displacements. Despite this, the torsional risk is the same, and it does not imply a significant change in the superstructure's design, so it could be enhanced by changing the substructure's stiffness.

A structure generally functions as a filter for seismic movement, that is, depending on the structure and its transfer function, it can be susceptible to the frequencies a certain earthquake. The transfer function, in turn, depends directly on the stiffness of the structure; when the structure is fixed at the base, it has more stiffness than it would with springs on it, but even so, this does not mean that the structure with springs at the base will have greater lateral displacements than the fixed structure, given that, when placing translational and rotational springs, vertical and lateral displacements and rotations will occur at the base, which can even reduce lateral displacement.

The shear forces and torsional moments increased and decreased, and so did the drifts, but the stiffness of the structure with springs decreased, which produced a reduction of shear forces in soils A and C, but increased with soil E, which is not the case for torsional moments, (it only increased for soils C and E). The explanation for this lies in the linear stiffness of the structure (translational and rotational). In the case of springs, the stiffness decreased, but the displacements increased, so there is a compensation comparable to the fixed model.

It is highly recommended to apply this study for other soil types and the same structure by optimizing the superstructure and substructure. Additionally, it is recommended to avoid displacements with higher variations at the base, which allows to control additional stresses on the superstructure.

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