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Evaluación y mejoramiento de la calidad de la potencia eléctrica usando un nuevo enfoque teórico

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Resumen

Las aplicaciones prácticas, tales como la incorporación de un nuevo enfoque teórico en la definición de estrategias de compensación instantánea y promediada para filtros activos de potencia en sistemas polifásicos y la descripción de un indicador global para la evaluación de la calidad de potencia, son introducidas en este artículo. Para alcanzar estas aplicaciones, una teoría generalizada de la potencia instantánea aplicada en sistemas no-sinusoidales, polifásicos y asimétricos es propuesta. El tensor de potencia instantánea se define en función del producto tensorial entre los vectores de tensión y corriente. Además, resultados simulados son incluidos.

Palabras clave: Compensador Activo de Potencia, Teoría de Potencia Instantánea, Sistemas Polifásicos, Producto tensorial

Improvement and assessment of the electrical power quality using a new theoretical approach

Abstract

Practical applications, such as the incorporation of the a new theoretical approach in the definition of the instantaneous and average compensation objectives for active power filters (*APFs*) in multiphase systems and the description of a global indicator for the evaluation of the power quality are introduced in this paper. In order to obtain these applications, a generalized theory of instantaneous power for nonsinusoidal unbalanced multiphase systems is proposed. The instantaneous power tensor is defined based on the tensor product between vectors of voltage and current. In addition, the simulated results are included.

Keywords: Active Power Compensator, Instantaneous Power Theory, Multiphase Systems, Tensor product

1. Introduction

There is an ever increase of nonlinear loads connected to electrical systems, where the injection of harmonic currents cause distortion of the voltage waveform complicating the analysis of electromagnetic phenomena. The traditional power theory based on the concept of the average value can not fully describe the electrical phenomena under these conditions. Therefore, the difficulty of defining a theory that describes the power for nonsinusoidal, unbalanced and multiphase systems entices researchers around the world (Depenbrock et al, 2003; Czarnecki, 2004; Morsi & El-Hawary, 2007; Leon & Cohen, 2008).

On the other hand, the physical meaning of the components of the instantaneous and apparent power in electrical systems is a topic that has been studied for many years and is still being studied today. Considerations such as harmonic effects and the imbalance of electrical signals in the power components in multiphase systems are currently under discussion and have originated a great deal of theories.

Theories about the transfer of power in multiphase systems have emerged since last beginning-century (Depenbrock, 1993). These theories show no constraints on the number of stages and the numbers of wires in the power systems. More recently, Willems, 1992 extends the instantaneous reactive power theory proposed by Akagi et al, 1984 to multiphase systems. In all these theories the authors propose the decomposition of the current in two orthogonal components. The first component is derived from the concept of instantaneous active power; while the second component is calculated as the complement to the previous component in order to obtain the total current. Therefore these theories do not present a formal definition of reactive power in multiphase systems.

Dai et al, 2004 proposed an alternative to define the concept of reactive power in multiphase systems which later is formalized (Salmerón & Herrera, 2009). This new approach defines the instantaneous reactive power from the definition of the exterior product in terms of the tensor

product. However, while in (Dai et al, 2004) a development for a system with the number of phase greater than three is not explicitly presented; in (Salmerón & Herrera, 2009) there is no reciprocity relation between the mathematical operations introduced to define the components of the current and each term of power.

A generalized instantaneous power theory is proposed following this tensor approach. The approach proposed in this paper emphasizes the possibility to formally define reactive power in nonsinusoidal unbalanced multiphase systems. Additionally, this paper presents the definition of instantaneous power in the context of tensor algebra as a derivation of circuit components (conductances and susceptances). Section 2 introduces the concept of tensor product, which allows the definition of instantaneous power tensor applied to nonsinusoidal, unbalanced and multiphase systems. Section 3 presents a tensor approach of the instantaneous reactive theory. This approach allows the definition of instantaneous and average compensation objectives in n-phase systems. Section 4 describes an indicator based on the instantaneous power tensor to evaluate the power quality.

2. Instantaneous power tensor theory

The proposed method is based on the definition of an evolutionary expression of instantaneous power, called "*instantaneous power tensor*" (Ustariz, 2010), in order to geometrically interpret the dynamic behavior of electromagnetic phenomena, analogous to studies of deformation in the mechanics of solids.

Therefore, the goal proposed is to obtain a single expression containing the two components of the instantaneous power (active and reactive). Therefore, using the dyadic or tensor product (Itskov, 2007) the proposed expression is as follows:

$$\mathcal{P}_{ij} = \vec{v}_i \otimes \vec{i}_j = \vec{v} \vec{i}^T \quad (1)$$

Where \wp_{ij} is the instantaneous power tensor and subscript T refers to the vector transpose. On the other hand, a multiphase electrical network was defined as one n -phase and m -wire power system related to the dimension of vector space, where voltage vector and current vector were defined assuming that, R^1 is the single-phase system, R^2 is the two-phase system with two-wire or three-wire, R^3 is the three-phase system with three-wire or four-wire and R^n is the multiphase system with n -phase and m -wire.

Therefore, in a system of n -phase and m -wire (see Figure 1), where the instantaneous vectors of voltage and current are expressed as:

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}, \quad \mathbf{i} = \begin{bmatrix} i_1 \\ i_2 \\ \vdots \\ i_m \end{bmatrix} \quad (2)$$

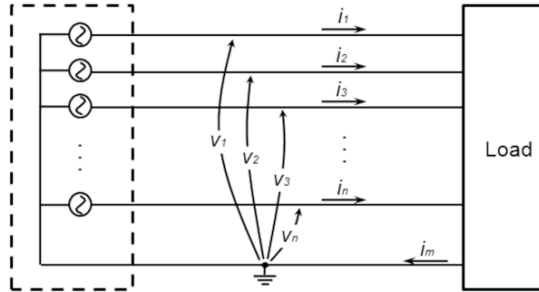


Figure 1: Multiphase system of n -phase and m -wire, R^n

Then, the instantaneous power tensor in R^n is equal to:

$$\wp_{ij} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} \otimes \begin{bmatrix} i_1 \\ i_2 \\ \vdots \\ i_m \end{bmatrix} = \begin{bmatrix} v_1 i_1 & v_1 i_2 & \dots & v_1 i_m \\ v_2 i_1 & v_2 i_2 & \dots & v_2 i_m \\ \vdots & \vdots & \ddots & \vdots \\ v_n i_1 & v_n i_2 & \dots & v_n i_m \end{bmatrix} \quad (3)$$

Moreover, in a system of three-phase and three-wire or four-wire, where the phases are identified by a - b - c , the instantaneous power tensor in R^3 is expressed as:

$$\wp_{ij} = \begin{bmatrix} v_a \\ v_b \\ v_c \end{bmatrix} \otimes \begin{bmatrix} i_a \\ i_b \\ i_c \end{bmatrix} = \begin{bmatrix} v_a i_a & v_a i_b & v_a i_c \\ v_b i_a & v_b i_b & v_b i_c \\ v_c i_a & v_c i_b & v_c i_c \end{bmatrix} \quad (4)$$

When $n=1$, it is the case of a single phase system, and the instantaneous values of voltage and current are scalars. Therefore, according to the traditional concept of instantaneous power in single phase systems the instantaneous power tensor in R^1 is equal to:

$$\wp_{ij} = v_a i_a \quad (5)$$

3. Tensor approach of the instantaneous reactive power

3.1 Orthogonal decomposition of the current vector

According to Ec.(1):

$$\wp_{ij}^T = (\vec{v} \vec{i}^T)^T = \vec{i} \vec{v}^T \quad (6)$$

This expression implies that the current vector can be obtained from the definition of instantaneous power tensor as follows:

$$\vec{i} = \frac{\wp_{ij}^T}{\vec{v} \cdot \vec{v}} \vec{v} = \frac{\wp_{ij}^T}{\|\vec{v}\|^2} \vec{v} \quad (7)$$

such that $\|\cdot\|$ denotes the Euclidean norm. Besides,

$$\wp_{ij}^T = \wp_{ij}^T + \wp_{ij} - \wp_{ij} \quad (8)$$

Now, replacing (7) in (8) the current vector can be expressed by,

$$\vec{i} = \frac{\wp_{ij}^T + \wp_{ij} - \wp_{ij}}{\vec{v} \cdot \vec{v}} \vec{v} = \frac{\wp_{ij}^T}{\vec{v} \cdot \vec{v}} \vec{v} + \frac{\wp_{ij} - \wp_{ij}}{\vec{v} \cdot \vec{v}} \vec{v} = \vec{i}_p + \vec{i}_q \quad (9)$$

Where, \vec{i}_p is the instantaneous active current vector:

$$\vec{i}_p = \frac{\wp_{ij}^T}{\vec{v} \cdot \vec{v}} \vec{v} = g_{ij} \vec{v} \quad (10)$$

and \vec{i}_q is the instantaneous reactive current vector:

$$\vec{i}_q = \frac{\wp_{ij} - \wp_{ij}^T}{\vec{v} \cdot \vec{v}} \vec{v} = b_{ij} \vec{v} \quad (11)$$

In Ec.(10) g_{ij} is the instantaneous conductance tensor:

$$g_{ij} = \frac{\varphi_{ij}}{\vec{v} \cdot \vec{v}} = \begin{bmatrix} \frac{v_1 i_1}{\|\vec{v}\|^2} & \frac{v_1 i_2}{\|\vec{v}\|^2} & L & \frac{v_1 i_n}{\|\vec{v}\|^2} \\ \frac{v_2 i_1}{\|\vec{v}\|^2} & \frac{v_2 i_2}{\|\vec{v}\|^2} & L & \frac{v_2 i_n}{\|\vec{v}\|^2} \\ M & M & O & M \\ \frac{v_n i_1}{\|\vec{v}\|^2} & \frac{v_n i_2}{\|\vec{v}\|^2} & L & \frac{v_n i_n}{\|\vec{v}\|^2} \end{bmatrix} \quad (12)$$

and in Ec. (11) b_{ij} is the instantaneous susceptance tensor:

$$b_{ij} = \frac{\varphi_{ij}^T - \varphi_{ji}}{\vec{v} \cdot \vec{v}} = \begin{bmatrix} 0 & \frac{v_2 i_1 - v_1 i_2}{\|\vec{v}\|^2} & \dots & \frac{v_n i_1 - v_1 i_n}{\|\vec{v}\|^2} \\ \frac{v_1 i_2 - v_2 i_1}{\|\vec{v}\|^2} & 0 & \dots & \frac{v_n i_2 - v_2 i_n}{\|\vec{v}\|^2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{v_1 i_n - v_n i_1}{\|\vec{v}\|^2} & \frac{v_2 i_n - v_n i_2}{\|\vec{v}\|^2} & \dots & 0 \end{bmatrix} \quad (13)$$

Moreover, the decomposition of the instantaneous current vector is characterized by:

$$\begin{aligned} \langle \vec{i}_p \cdot \vec{i}_q \rangle &= \vec{i}_p^T \vec{i}_q = (g_{ij} \vec{v})^T (b_{ij} \vec{v}) = \vec{v}^T \frac{\vec{i} \vec{v}^T}{\vec{v}^T \vec{v}} \left(\frac{\vec{i} \vec{v}^T - \vec{v} \vec{i}^T}{\vec{v}^T \vec{v}} \right) \vec{v} \\ &= \frac{(\vec{v}^T \vec{i})(\vec{v}^T \vec{i}) \vec{v}^T \vec{v} - (\vec{v}^T \vec{i}) \vec{v}^T \vec{v} (\vec{i}^T \vec{v})}{(\vec{v}^T \vec{v})^2} \\ &= \frac{(\vec{v}^T \vec{i})^2}{(\vec{v}^T \vec{v})^2} (\vec{v}^T \vec{v} - \vec{v}^T \vec{v}) = 0 \end{aligned} \quad (14)$$

such that,

$$\|\vec{i}\|^2 = \|\vec{i}_p\|^2 + \|\vec{i}_q\|^2 \quad (15)$$

3.2 Orthogonal decomposition of the power tensor

The decomposition of the instantaneous power tensor is obtained by applying the tensor product of the voltage vector on Ec. (9), thus:

$$\vec{v} \otimes \vec{i} = \vec{v} \otimes (\vec{i}_p + \vec{i}_q) = \vec{v} \otimes \vec{i}_p + \vec{v} \otimes \vec{i}_q \quad (16)$$

Here, the first term is the instantaneous active power tensor:

$$^p \varphi_{ij} = \vec{v} \otimes \vec{i}_p = \vec{v} \otimes (g_{ij} \vec{v}) = \vec{v} \otimes (\vec{v} g_{ij}^T) = (\vec{v} \otimes \vec{v}) g_{ij}^T \quad (17)$$

and the second term is the instantaneous reactive power tensor:

$$^q \varphi_{ij} = \vec{v} \otimes \vec{i}_q = \vec{v} \otimes (b_{ij} \vec{v}) = \vec{v} \otimes (\vec{v} b_{ij}^T) = (\vec{v} \otimes \vec{v}) b_{ij}^T \quad (18)$$

Consequently,

$$\varphi_{ij} = ^p \varphi_{ij} + ^q \varphi_{ij} \quad (19)$$

Moreover, Ec. (19) satisfies the orthogonality concept, in other words,

$$\begin{aligned} \langle ^p \varphi_{ij} \cdot ^q \varphi_{ij} \rangle &= \text{tr} \left(^p \varphi_{ij}^T ^q \varphi_{ij} \right) = \text{tr} \left(\frac{\vec{v} \vec{v}^T}{\vec{v}^T \vec{v}} \vec{v} \vec{v}^T \left(\frac{\vec{v} \vec{v}^T}{\vec{v}^T \vec{v}} \vec{v} \vec{v}^T - \vec{v} \vec{v}^T \frac{\vec{v} \vec{v}^T}{\vec{v}^T \vec{v}} \right) \right) \\ &= \text{tr} \left(\frac{\vec{v} \vec{v}^T \vec{v} (\vec{v}^T \vec{v}) \vec{v}^T \vec{v} - \vec{v} \vec{v}^T \vec{v} (\vec{v}^T \vec{v}) \vec{v}^T \vec{v}}{(\vec{v}^T \vec{v})^2} \right) \\ &= \text{tr} \left(\vec{v} (\vec{i}^T \vec{v}) \vec{i}^T - \frac{\vec{v} (\vec{i}^T \vec{v}) (\vec{v}^T \vec{i}) \vec{v}^T}{\vec{v}^T \vec{v}} \right) \\ &= \vec{i}^T \vec{v} \left(\text{tr} (\vec{v} \vec{v}^T) - \frac{\vec{v}^T \vec{i}}{\vec{v}^T \vec{v}} \text{tr} (\vec{v} \vec{v}^T) \right) \\ &= \vec{i}^T \vec{v} \left(\vec{v}^T \vec{v} - \frac{\vec{v}^T \vec{i}}{\vec{v}^T \vec{v}} \vec{v}^T \vec{v} \right) = 0 \end{aligned} \quad (20)$$

Here, the tr operator corresponds to the sum of the main diagonal elements (trace). Therefore, the decomposition of the instantaneous power tensor satisfies the following orthogonal relation:

$$\|\varphi_{ij}\|^2 = \|^p \varphi_{ij}\|^2 + \|^q \varphi_{ij}\|^2 \quad (21)$$

The importance of the new formulation is based on the fact that the expression for the instantaneous reactive power in multiphase systems is known, thanks to the decomposition of the tensor power, given in (19). Now, thanks to know the expression of instantaneous reactive power, there are other compensation strategies possible for the reference currents estimate for the control of active power filters, regardless of the number of phases of the power system (e.g. reactive power cancellation and distortion power cancellation).

The expression given in (21) is equivalent to the vector formula of the generalized instantaneous

reactive power theory proposed by Willems 1992, where the instantaneous apparent power is defined as:

$$s^2 = p^2 + q^2 \quad (22)$$

With p defined as the instantaneous power transmitted to the load (instantaneous active power), thus:

$$p = \vec{v} \cdot \vec{i} = v_1 i_1 + v_2 i_2 + L + v_n i_n \quad (23)$$

and q as the instantaneous imaginary power (instantaneous reactive power), determined by:

$$q = \|\vec{v}\| \|\vec{i}_q\| = \|\vec{v}\| \|\vec{i} - \vec{i}_p\| \quad (24)$$

Where,

$$\vec{i}_p = \frac{p}{\|\vec{v}\|^2} \vec{v} \quad (25)$$

Therefore, the following equivalences are established:

$$s = \|\varphi_{ij}\|; \quad p = \|\varphi_{ij}^p\|; \quad q = \|\varphi_{ij}^q\| \quad (26)$$

4. Power quality improvement using instantaneous power tensor

This section has a number of control strategies for active power filters (APFs), which can be implemented using the proposed tensor formulation. Table 1 shows a summary of the possible compensation objectives from the point of view of power in electrical systems (Montero et al, 2007; Salmerón & Litran, 2010).

Given these possible compensation objective, the instantaneous vector of the referent current is defined as:

$$\vec{i}_{(ref)} = \frac{p \varphi_{ij}^{T(ref)}}{\vec{v} \cdot \vec{v}} \vec{v} + \frac{q \varphi_{ij}^{T(ref)}}{\vec{v} \cdot \vec{v}} \vec{v} \quad (27)$$

Moreover, of the various options of the reference tensor shown in Table 1, ${}^p \tilde{\varphi}_{ij}$ is the variable term of the instantaneous active power tensor defined by:

$${}^p \tilde{\varphi}_{ij} = {}^p \varphi_{ij} - {}^p \bar{\varphi}_{ij} = {}^p \varphi_{ij} - (\vec{v} \otimes \vec{v}) G_{ij}^T = (\vec{v} \otimes \vec{v}) (g_{ij}^T - G_{ij}^T) \quad (28)$$

Where G_{ij} is the equivalent conductance tensor defined by:

$$G_{ij} = \frac{\text{tr} \left(\frac{1}{T} \int_T {}^p \varphi_{ij} dt \right)}{\vec{v} \cdot \vec{v}} \delta_{ij} \quad (29)$$

With δ_{ij} defined as the “Kronecker's delta tensor” and used to construct the equivalent conductance tensor. While ${}^q \tilde{\varphi}_{ij}$ is the variable term of instantaneous reactive power, defined as:

$${}^q \tilde{\varphi}_{ij} = {}^q \varphi_{ij} - {}^q \bar{\varphi}_{ij} = {}^q \varphi_{ij} - (\vec{v} \otimes \vec{v}) B_{ij}^T = (\vec{v} \otimes \vec{v}) (b_{ij}^T - B_{ij}^T) \quad (30)$$

where B_{ij} is the equivalent susceptance tensor defined by:

$$B_{ij} = \frac{\frac{1}{T} \int_T {}^q \varphi_{ij} dt}{\vec{v} \cdot \vec{v}} \quad (31)$$

The block diagram of the control strategies for the determination of APF reference compensation currents is shown in Figure 2, where the compensation objectives selector block was implemented.

Table 1: Compensation Objectives in Electrical network

Compensation objective –Power	Reference Tensor	
	${}^p \varphi_{ij}^{T(ref)}$	${}^q \varphi_{ij}^{T(ref)}$
Instantaneous reactive–IR	0	${}^q \varphi_{ij}$
Oscillating reactive–OR	0	${}^q \tilde{\varphi}_{ij}$
Oscillating active and oscillating reactive –OA/OR	${}^p \tilde{\varphi}_{ij}$	${}^q \tilde{\varphi}_{ij}$
Oscillating active and instantaneous reactive –OA/IR	${}^p \tilde{\varphi}_{ij}$	${}^q \varphi_{ij}$

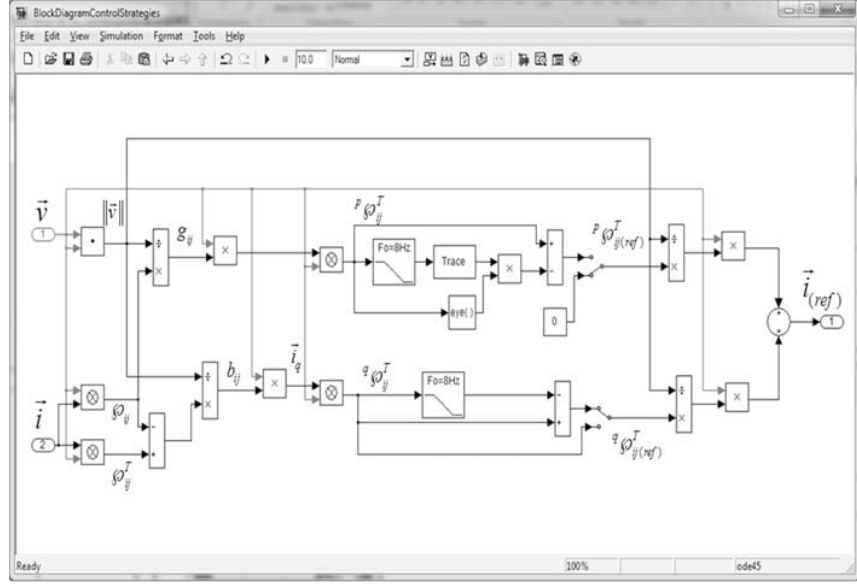


Figure 2: Block diagram of the control strategies for determination of APF reference current.

The different objectives of compensation have been applied to a nonlinear six-phase system. In this circuit, a sinusoidal and balanced three phase voltage source, feeds a triple wound transformer Y, Y ϕ . The secondary winding feeds a twelve pulse controller rectifier operating with a firing angle of 45° with a source of current at the dc side assumed as load (Figure 3). This system was chosen because it is a practical case where six-phase waveforms can be identified.

The circuit shown in Figure 3 has been implemented in Matlab-Simulink. The active power filter is modeling as an ideal current source controlled by the referent current obtained with the proposed tensor formulation.

Figures 4 to 7 show the simulation results for the different compensation objectives. The voltage and current waveforms in these figures correspond to the first phase (phase-a in three-phase side and phase-1 in six-phase side). In addition, $t=50ms$ is the time in which the active filter is connected to the system. For all cases, the information is organized as follows.

Three-phase system (transformer primary side):

- (a) Voltage waveform, v_a
- (b) Current waveform, i_a
- (c) Active current waveform, $i_{p,a}$
- (d) Reactive current waveform, $i_{q,a}$
- (e) Instantaneous active power, $\| \delta_{ij}^p \|_{3 \times \phi}$
- (f) Instantaneous reactive power, $\| \delta_{ij}^q \|_{3 \times \phi}$

Six-phase system (transformer secondary side):

- (g) Voltage waveform, v_l
- (h) Current waveform, i_l
- (i) Active current waveform, $i_{p,l}$
- (j) Reactive current waveform, $i_{q,l}$
- (k) Instantaneous active power, $\| \delta_{ij}^p \|_{6 \times \phi}$
- (l) Instantaneous reactive power, $\| \delta_{ij}^q \|_{6 \times \phi}$

The simulation results for the compensation objective IR are shown in Figure 4 and summarized in the third column of Table 2. Here, the instantaneous reactive power is completely

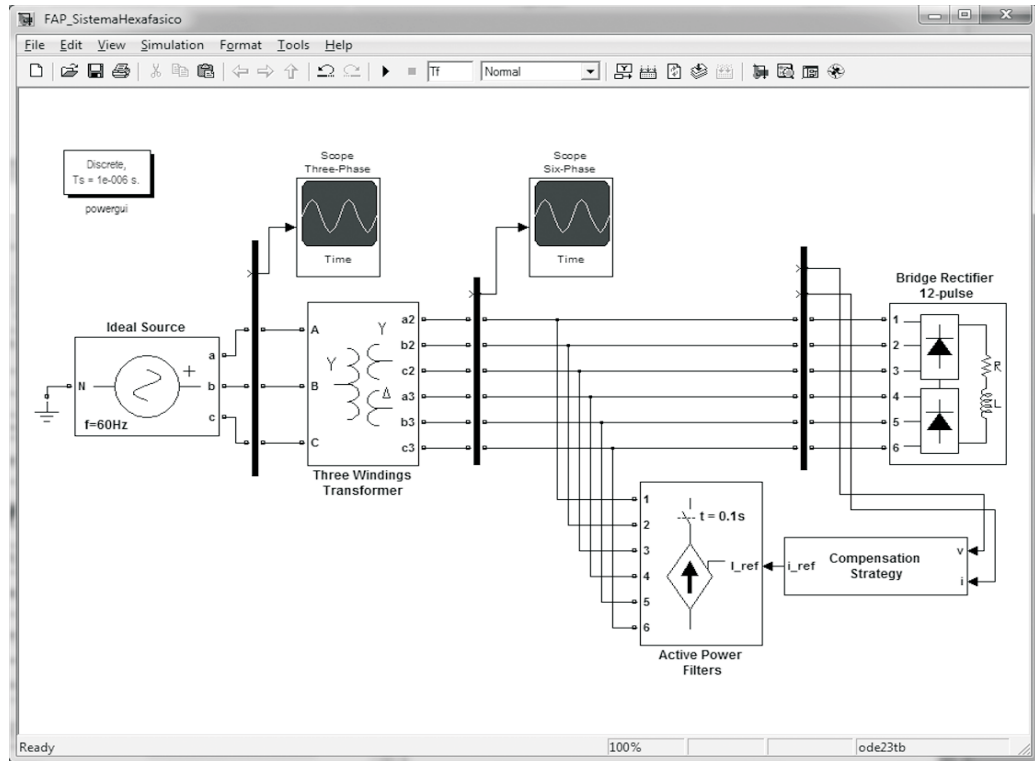


Figure 3. Three-phase to six-phase system compensated by a shunt APF implemented in MATLAB-Simulink

removed both on three-phase and six-phase side when the active filter is connected. Therefore, the instantaneous reactive power is fully compensated when the active filter is connected, while the delivered instantaneous active power equals the instantaneous active power consumed by the load. Regarding distortion, it's observed that the waveform of the current signals change but the total harmonic distortion not improvement.

The simulation results for the compensation objective OR are shown in Figure 5 and summarized in the fourth column of Table 2. Now, when the active filter is connected, only the oscillating portion of the instantaneous reactive power is compensated thus, the source has to continue generating a constant instantaneous reactive power. The instantaneous active power delivered by the source remains equal to the instantaneous active power consumed by the load.

From the results shown in Figure 5, the instantaneous reactive current is delayed exactly by 90° with the voltage both on three-phase and six-phase side when the active filter is connected.

The simulation results for the compensation objective OA/OR are shown in Figure 6 and summarized in the fifth column of Table 2. Here, the oscillating active and reactive powers are simultaneously compensated when the active filter is connected. This time, the waveform of the current is sinusoidal but still keeps the phase shift obtained in the compensation objective OR . From the results shown in Figure 6, the instantaneous active current is perfectly in phase with the voltage and instantaneous reactive current is delayed exactly by 90° with the voltage both on three-phase and six-phase side when the active filter is connected.

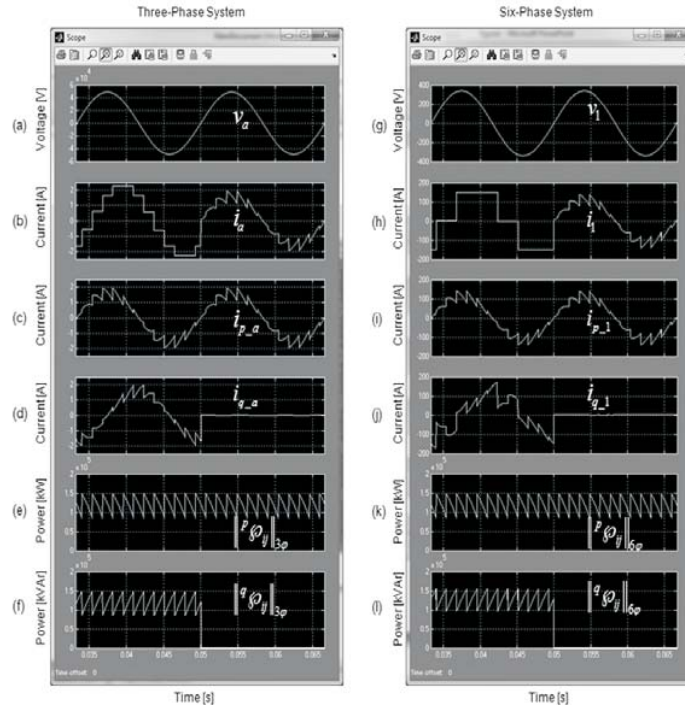


Figure 4. Simulation results: compensation objective IR

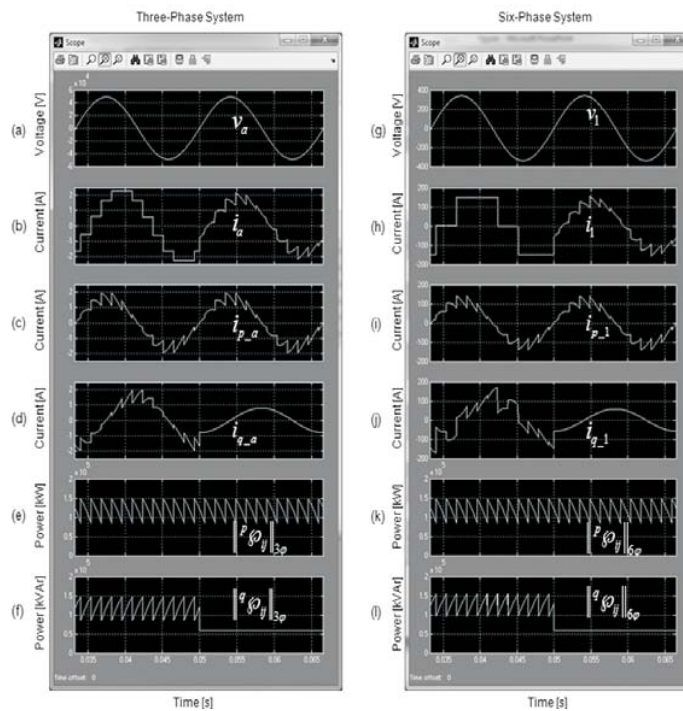


Figure 5. Simulation results: compensation objective OR

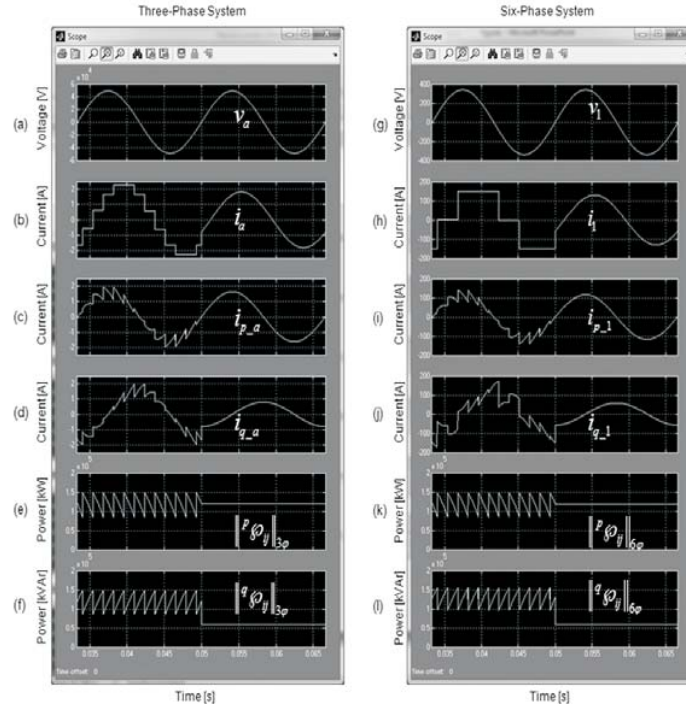


Figure 6. Simulation results: compensation objective OA/OR

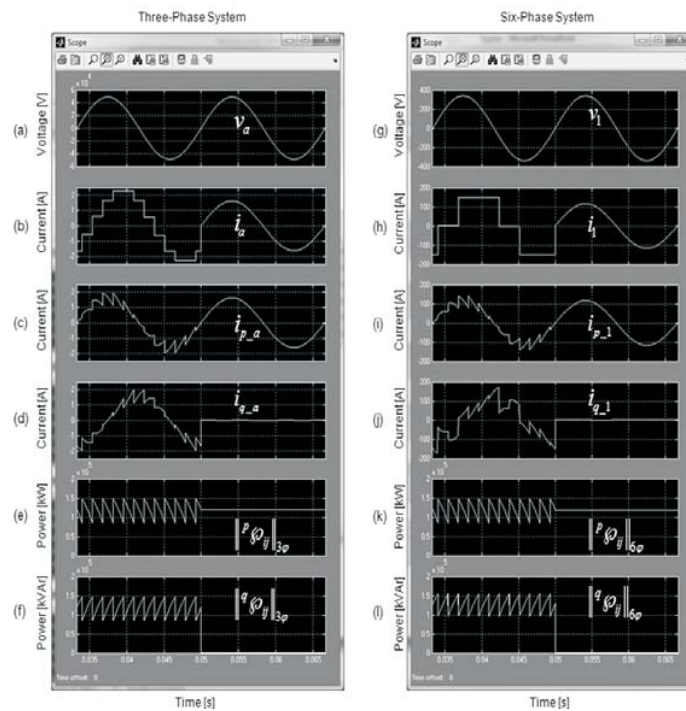


Figure 7. Simulation results: compensation objective OA/IR

Table 2: Summary of the Simulation Results

Factor	i_{load}	$i_{p(IR)}$	$i_{p(OR)}$	$i_{p(OA/OR)}$	$i_{p(OA/IR)}$
I_{rms} [A]	1.650	1.169	1.303	1.291	1.156
I_f [A]	1.631	1.156	1.291	1.291	1.156
THD_I [%]	15.20	15.18	13.59	0.000	0.000
dPF	0.710	1.000	0.895	0.896	1.000
P [kW]	119.8	119.8	119.8	119.8	119.8
S_v [kVA]	170.8	121.0	134.9	133.6	119.8
PF	0.702	0.989	0.887	0.896	1.000

The simulation results for the compensation objective OA/IR are shown in Figure 7 and summarized in the sixth column of Table 2. Now, the oscillating active power and the instantaneous reactive power are compensated when the active filter is connected. In this compensation objective the waveform of the current signal is also sinusoidal. In addition the voltage and current signals are in phase.

From the results shown in Table 2, as expected, the only strategy which gets to compensate the combined effect is the correspondent to the compensation objective OA/IR . The result of this strategy is the closer to the ideal system.

The terms relating to power concepts in the Table 2 are based on the new definitions of power, proposed by the IEEE Working Group on Nonsinusoidal Situations as collected in the IEEE Standard 1459-2000 (Emanuel, 2004).

5. Power quality assessment using instantaneous power tensor

5.1 Conventional indices for power quality assessment

The first step toward power quality assessment is the definition of power quality indices able to quantify the deviation from an ideal reference situation and quantify the detrimental effects of this deviation (Cristaldi et al, 2002; Dell'Aquila et al, 2004; Lin & Domijan, 2005; Shin et al, 2006; Ferrero, 2008). Traditionally, in stationary state

the power quality assessment is based on individual indicators such as total harmonic distortion THD_I , load current unbalance factor UF and reactive factor QF . Also, the maximum value between these indices is chosen as a global indicator of power quality GI , thus:

$$THD_I = \max \left(\frac{\sqrt{\sum I_{h(a)}^2}}{I_{1(a)}}, \frac{\sqrt{\sum I_{h(b)}^2}}{I_{1(b)}}, \frac{\sqrt{\sum I_{h(c)}^2}}{I_{1(c)}} \right) \quad (32)$$

$$UF = \frac{-I_1}{+I_1} \quad (33)$$

$$QF = \frac{Q_{1(a)} + Q_{1(b)} + Q_{1(c)}}{P_a + P_b + P_c} \quad (34)$$

$$GI = \max(THD_I, UF, QF) \quad (35)$$

where, the $I_{h(k)}$ is the current harmonic in the phase- k ($k=a,b,c$), I_1 and $+I_1$ are the fundamental negative and positive sequence components and $Q_{1(k)}$ is the fundamental reactive power of phase- k .

5.2 Symmetrical and anti-symmetrical decomposition

Section III introduces a decomposition of the instantaneous power tensor focused on the division of the instantaneous current vector into two orthogonal components: the first component in phase with the voltage vector, which is related to the instantaneous active power and the other

component related to the instantaneous reactive power. This section defines another tensor decomposition, taking into account that any second order tensor can be unequivocally expressed as the sum of a symmetric tensor and an anti-symmetric thus:

$$\wp_{ij} = \frac{1}{2}[\wp_{ij} + \wp_{ij}^T] + \frac{1}{2}[\wp_{ij} - \wp_{ij}^T] \quad (36)$$

This expression can be written in compact form, as:

$$\wp_{ij} = {}^{sym}\wp_{ij} + {}^{ant}\wp_{ij} \quad (37)$$

The operation leading from an arbitrary tensor with components \wp_{ij} to the tensor with components $\wp_{ij} \wp_{ij}^T$ is called symmetrization, while the operation leading to the tensor with components $\wp_{ij} \wp_{ij}^T$ is called anti-symmetrization.

The concept of symmetrization in electrical systems corresponding to the definition of symmetrical or ideal circuits is introduced, in the next item, using this decomposition.

5.3 Deviation factor of power quality based on the tensor analysis

Now, a single discriminating factor to power quality assessment is proposed based on the symmetrical and anti-symmetrical decomposition of instantaneous power tensor. This factor afterwards could be used to penalize or to compensate the customers at the *point of common coupling* (PCC), similarly as the power factor has been used.

Establishing this factor implies to define the ideal power system as one circuit composed of a balanced and sinusoidal voltage source (reference source) supplying a resistive balanced load (reference load). Any situation producing nonconformity with respect to these ideal conditions supposes a quality loss. Moreover, this

ideal circuit is the unique power system that presents a totally symmetric instantaneous power tensor.

The evaluation of these nonconformities can be quantified through the definition of a new power quality index, named instantaneous deviation indicator of power quality IDI_{pq} , stated by

$$IDI_{pq} = \sqrt{\frac{\sum_{i=1}^n \sum_{j=1}^n (\wp_{ij} - {}^{ideal}\wp_{ij})^2}{\sum_{i=1}^n \sum_{j=1}^n {}^{ideal}\wp_{ij}^2}} \quad (38)$$

and next, the deviation factor of power quality defined as:

$$DF_{pq} = \sqrt{\frac{1}{T} \int_T (IDI_{pq})^2 dt} \quad (39)$$

In the Eq (38) the term ${}^{ideal}\wp_{ij}$ corresponds to the instantaneous power tensor of the ideal power system (tensor totally symmetric). The ideal instantaneous power tensor is calculated as follows:

$${}^{ideal}\wp_{ij} = \vec{v}_f^+ \otimes \vec{i}_{f(activ)}^+ = \vec{v}_f^+ \otimes \frac{\text{tr}(\vec{\wp}_{ij})}{\frac{1}{T} \int_T (\vec{v}_f^+ \vec{v}_f^+)} \vec{v}_f^+ = (\vec{v}_f^+ \otimes \vec{v}_f^+) G_{(ideal)} \quad (40)$$

where v_f^+ is the voltage vector with a single fundamental positive-sequence component and $G_{(ideal)}$ is the equivalent conductance of the ideal power system.

In this paper, the power quality assessment approach proposed based on the instantaneous power tensor theory has been applied to a three-phase, four-wire system. The analyzed electrical network is similar to the one presented in Figure 8. The electrical network was simulated in ATP-EMTP. In addition, the DF_{pq} index is in contrasted against the GI index. For comparison proposes,

several simulations done using both ideal and distorted voltage under different load current conditions. The details of each load connected at the PCC are shown in Figure 9.

The RMS values of the voltage and the values of the parameters of the power system under study are shown in Table 3. The system impedance is assumed to be of a resistance of $0.892 \text{ m } \Omega$ in series with an inductance of 0.016 mH .

Table 4 shows a summary of the simulated cases. In the Table 4, the script “on” refers to the connection of the source or disturbing load in the PCC, while the script “off” refers to the non-connection. Figure 10 shows the voltage and current waveforms measurement in the case H.

Table 5 shows the values of the individual conventional indicators used in the evaluation of the power quality in each of the simulated cases.

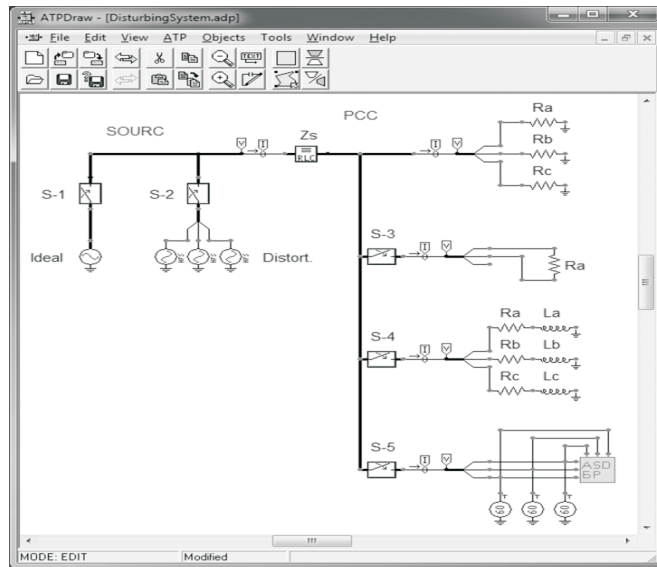


Figure 8. The studied example implemented in ATP-EMTP

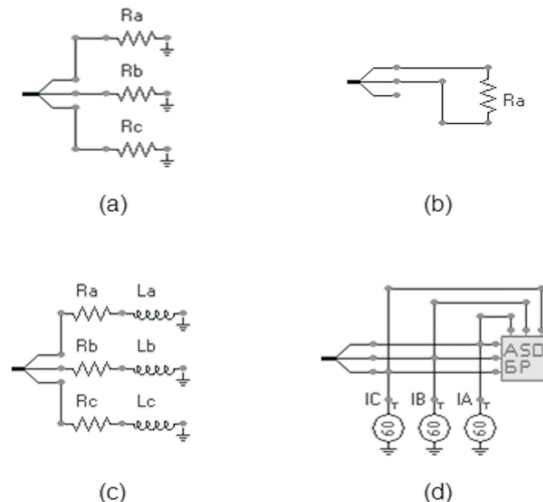


Figure 9. Three-phase loads connected in the studied example: (a) ideal load, (b) disturbing load #1 (unbalanced), (c) disturbing load #2 (inductive) and (d) disturbing load #3 (nonlinear).

Table 3: System Parameters

Supply	Ideal	Distorted		
		Fundamental	3 rd harmonic	
V_a [V _{rms}]	220 ∠0°	201 ∠0°	35.07 ∠0°	
V_b [V _{rms}]	220 ∠-120°	220 ∠-120°	46.21 ∠0°	
V_c [V _{rms}]	220 ∠-240°	220 ∠-240°	46.21 ∠0°	
Load	Ideal	Disturbing		
		#1	#2	#3
R_a [Ω]	1.32	2.67	1.17	—
R_b [Ω]	1.32	—	1.17	—
R_c [Ω]	1.32	—	1.17	—
L_a [mH]	—	—	2.53	—
L_b [mH]	—	—	2.53	—
L_c [mH]	—	—	2.53	—
I_a (fundamental) [A _{rms}]	—	—	—	107 ∠51°
I_a (5 rd harmonic) [A _{rms}]	—	—	—	63 ∠76°
I_a (7 rd harmonic) [A _{rms}]	—	—	—	33 ∠-2°

Table 4: Summary of Simulated Cases

Case	Source		Disturbing load			
	Switch S-1	Switch S-2	Switch S-3	Switch S-4	Switch S-5	
<i>A</i>	on	off	on	off	off	
<i>B</i>	on	off	off	on	off	
<i>C</i>	on	off	off	off	on	
<i>D</i>	on	off	on	on	on	
<i>E</i>	off	on	on	off	off	
<i>F</i>	off	on	off	on	off	
<i>G</i>	off	on	off	off	on	
<i>H</i>	off	on	on	on	on	

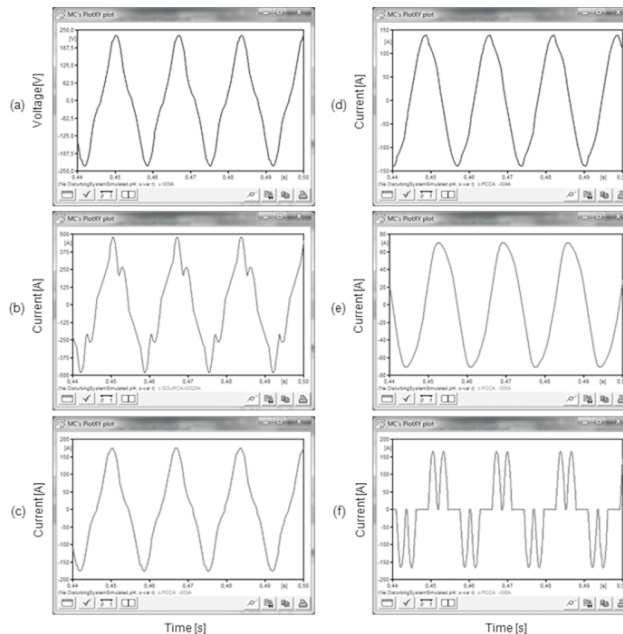


Figure 10. Voltage and current waveform for the case H: (a) PCC voltage, (b) PCC current, (c) ideal load current, (d) unbalanced load current (e) inductive load current and (f) nonlinear load current.

Table 5: Summary of Simulation Results: Individual Indices

Case	PCC			Disturbing load		
	THD_l [%]	UF [%]	QF [%]	THD_l [%]	UF [%]	QF [%]
<i>A</i>	0.23	33.08	0.00	0.23	100.00	0.00
<i>B</i>	0.90	0.25	32.93	0.89	0.25	81.52
<i>C</i>	19.80	0.24	0.01	59.73	0.22	0.03
<i>D</i>	12.52	17.93	20.75	21.92	27.93	33.25
<i>E</i>	21.06	31.71	0.00	3.45	100.00	0.00
<i>F</i>	14.52	3.17	32.07	10.20	3.03	80.74
<i>G</i>	18.34	2.95	-10.29	62.35	3.38	-37.80
<i>H</i>	15.72	17.62	15.81	28.32	29.10	26.37

These results allow calculating of the global index GI .

Table 6 shows a comparative summary between the GI index and the DF_{pq} factor for each of the cases. From the comparisons it can be said that:

§ The global GI index and the DF_{pq} deviation factor are very similar when the power supply is sinusoidal balanced (ideal supply) and the load connected to PCC is only unbalanced, inductive or nonlinear (case: *A*, *B* and *C*).

§ There are differences between the DF_{pq} deviation factor and the GI global index when the power supply is not sinusoidal (case: *E*, *F* and *G*). These differences are increased when different disturbing loads are connected simultaneously to the PCC (case: *D* and *H*).

§ The DF_{pq} deviation factor provides a better alternative for the evaluation of a non-conformity

regarding the electrical systems ideal condition. This assertion is based on the fact that DF_{pq} evaluates more rigorously the loss of power quality when multiple disturbances affect simultaneously an electrical network, regardless of whether the disturbance arises from the load or from source.

6. Conclusion

The introduced mathematical tool proposes a way to calculate the instantaneous power components and the current decomposition in an active and a reactive component, based on a formal definition of reactive power in multiphase electric systems. This new formulation also allows the definition of instant compensation objectives in n -phase systems, based on the fact that the expression for the instantaneous reactive power in multiphase systems is known thanks to the orthogonal decomposition of the power tensor. This new approach allows the reduction of construction

Table 6: Summary of Simulation Results: Global Indices

Case	PCC		Disturbing load	
	GI [%]	FD_{pq} [%]	GI [%]	FD_{pq} [%]
<i>A</i>	33.08	33.07	100.00	100.00
<i>B</i>	32.93	31.90	81.52	80.48
<i>C</i>	19.80	19.57	59.73	59.38
<i>D</i>	20.75	29.16	33.25	47.11
<i>E</i>	31.71	40.13	100.00	105.70
<i>F</i>	32.07	40.19	80.74	84.65
<i>G</i>	18.34	28.41	62.35	82.66
<i>H</i>	17.62	32.53	29.10	49.02

costs of the APFs, given that now APFs can be designed at low voltages in the case of rectifiers of twelve, eighteen, twenty four and more pulses. A single DF_{pq} index has been proposed as the basis of the power quality assessment based on the instantaneous power tensor theory. The deviation indicator of power quality proved to be successful, as found by comparisons made between the ideal power system introduced and many other typical loads selected from a variety of test cases. So, the New Theoretical Approach does not present any problem to be used as the base of an active power filter control algorithm or a global index for power quality assessment, with any voltage conditions in the point of common coupling (PCC). The results have been corroborated by the correspondent simulations in the Matlab-Simulink and ATP-EMTP environments.

7. List of Symbols

$\langle \cdot \rangle$	scalar product
\times	vector product
\otimes	tensor product
$\ \cdot \ $	norm
$\text{tr}(\cdot)$	trace
$(\cdot)^T$	transpose
\vec{v}	instantaneous voltage vector
\vec{i}	instantaneous current vector
p	instantaneous active power
q	instantaneous reactive power
g_{ij}	instantaneous conductance tensor
b_{ij}	instantaneous susceptance tensor
φ_{ij}	instantaneous power tensor
$G_{e_{ij}}$	equivalent conductance tensor
$B_{e_{ij}}$	equivalent susceptance tensor
${}^{ideal}\varphi_{ij}$	ideal power tensor
DF_{pq}	deviator factor of the power quality

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