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An Analysis of the Initiation Process of Electro-explosive **Devices**

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Abstract: Electro-explosive devices (an electric resistance encapsulated by a primary explosive) fundamentally convert electrical energy into thermal energy, to start off an explosive chemical reaction. Obviously, the activation of those devices shall not happen by accident or, even worse, by intentional exogenous influence. From an ordinary differential equation, which describes the electro-explosive thermal behavior, a remarkable, but certainly not intuitive, dependence of the temperature response on the time constant of the heat transfer process is verified: the temperature profile dramatically changes as the time constant spans a wide range of values, from much lesser than the pulse width to much greater than the pulse period. Based on this dependence, important recommendations, concerning the efficient and safety operation of electro-explosive devices, are proposed.

Keywords: Electro-Explosive Devices, Squib, Thermal Model, Pulsed Initiation, Temperature Stacking.

LIST OF SYMBOLS

$a = 1/\tau_{EE}$	Inverse of the EED time constant	(s ⁻¹)	t	Time
ave	Average	()	T	Pulse period
b	Barrel	()	THRESHOLD	Ignition temperature threshold
C_T	EED thermal capacitance	$(J.^{o}C^{-1})$	^	And
-	Duty-Cycle	()		Exponent (non-linear hydraulic
EE	Electro-explosive	()	γ	resistance)
11	Height of the water column inside the	(***)	η	Operational efficiency (temperature gain)
П	barrel	(111)	0	EED temperature increment (above
H_{h}	Height of the barrel	(m)	0	ambient temperature)
i	Input	()	π	≈3.1415
n	Cycle counting (pulsed excitation)	()	ρ	Water density
0	Output	()	$ au_b$	Barrel time constant
P_{ave}	Average power	(W)	$ au_{EE}$	EED time constant
$P_{i}(t)$	EED electrical input power	(W)		
P_{p}	Peak power	(W)	INTRODUCTION In order to study the ignition process of electrodevices (EEDs), a consistent model is needed, one coherently reproducing the temperatures of EDDs in to the electrical power applied to them. In fact, EED	
P_{W}	Pulse width	(s)_		
Q_i	Input volumetric flow rate	$(m^3.s^{-1})$		
Q_o	Output volumetric flow rate	$(m^3.s^{-1})$		
r	Radius of the barrel	(m)		
R	Hydraulic resistance	(m ⁻² .s)		
$R_{_T}$	Thermal resistance	(°C-1.W)		
	b C_{T} $DC = P_{W}/T$ EE H H_{b} i n o P_{ave} $P_{i}(t)$ P_{p} P_{W} Q_{i} Q_{o} r R	aveAverage b Barrel C_T EED thermal capacitance $DC = P_W/T$ Duty-Cycle EE Electro-explosive H Height of the water column inside the barrel H_b Height of the barrel i Input n Cycle counting (pulsed excitation) o Output P_{ave} Average power $P_i(t)$ EED electrical input power P_P Peak power P_W Pulse width Q_i Input volumetric flow rate Q_o Output volumetric flow rate R Hydraulic resistance	aveAverage() b Barrel() C_T EED thermal capacitance $(J.^{\circ}C^{-1})$ $DC = P_W/T$ Duty-Cycle() EE Electro-explosive() H Height of the water column inside the barrel(m) I Input() n Cycle counting (pulsed excitation)() o Output() P_{ave} Average power(W) $P_i(t)$ EED electrical input power(W) P_P Peak power(W) P_W Pulse width(s)_ Q_i Input volumetric flow rate(m³.s-¹) r Radius of the barrel(m) R Hydraulic resistance(m-².s)	aveAverage() T b Barrel() $THRESHOLD$ C_T EED thermal capacitance $(J.^{\circ}C^{-1})$ $^{\wedge}$ $DC = P_W/T$ Duty-Cycle() $^{\vee}$ EE Electro-explosive() $^{\vee}$ H Height of the water column inside the barrel(m) $^{\vee}$ H_b Height of the barrel(m) $^{\vee}$ i Input() $^{\vee}$ n Cycle counting (pulsed excitation)() $^{\vee}$ o Output() $^{\vee}$ P_{ave} Average power(W) $^{\vee}$ P_{ave} Average power(W) $^{\vee}$ $P_{i}(t)$ EED electrical input power(W) P_{p} Peak power(W) P_{p} Peak power(W) P_{w} Pulse width(s)_ Q_i Input volumetric flow rate $(m^3.s^{-1})$ In order to devices (EED coherently regions) Q_o Output volumetric flow rate $(m^2.s)$ In order to devices (EED coherently regions) R Hydraulic resistance $(m^2.s)$ $(m^2.s)$

 (m^3)

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Volume of water inside the barrel

gnition process of electro-explosive ent model is needed, one capable of e temperatures of EDDs in response applied to them. In fact, EEDs merely convert energy from one type to another, which means that their electro-thermal model is a direct consequence of the energy conservation principle.

There is a complete theory behind such model and it is founded on Rosenthal's (1961) and Prince & Leeuw's (1988) work. Hoberman (1965) and Potter & Scott (2004) developed

(s) (s)

(---) (---)

(°C)

(---) (kg.m-3)

(s)

(s)

a comprehensive study of this matter too. However, as the focus here is on the application of the model, not in the theory sustaining it, only the necessary level of abstraction will be retained from the original effort of those researchers and authors.

From the solution of that model, an outstanding advantage, in terms of temperature gain, will be noticed in favor of the electrical pulsed excitation (time to ignition not been a problem) whenever the width and period of the train of pulses are adjusted, taking into consideration the EED thermal time constant $\tau_{\rm EE}$. Thus the choice of the most appropriate power source (continuous or pulsed) to drive a specific EED will be primarily affected by its thermal time constant. Accordingly, the thorough knowledge of this constant will be essential for reliable and risk free (secure) applications of EEDs.

In this way, the steps to be followed to succeed in reaching the analysis of the EED ignition are: to adopt a simplified version of the currently used electro-thermal model of EEDs (an ordinary differential equation – an ODE, for short); to solve that model for different sorts of excitation (continuous and pulsed); and to verify the strong influence of both the EED (thermal time constant) and power source (pulse width and period of the train of pulses) parameters in the EED temperature response.

It follows that the key objective of the analysis to be carried out later in this paper is to guide users of EEDs, when faced with the choice of the right source of power to the right squib (vice-versa).

But, before analyzing the electro-explosive as an energy converter device, the investigation of a topic much more familiar to everyone, the barrel problem (Moran and Shapiro, 2008), can be valuable.

A CONVENIENT ANALOGY

Consider a barrel (a cylinder with transversal area, πr^2 , height, H_b , and top surface removed), initially empty, having a small hole in its base. Assume a given steady water flow into the barrel. Naturally, a question will arise: how is the level of the water inside the barrel going to evolve as a function of time?

To facilitate the analysis of this problem, let the hole at the barrel base be modeled by a linear hydraulic resistance R (actually, $R = R_0 \cdot H^{(1-\gamma)}$, with γ adjusted in accordance with each specific situation (Cochin, 1980), and let the water flux through the hole, Q_{α} , be proportional to H:

$$Q_0 = \frac{H}{R} = \frac{H}{R_0 \cdot H^{(1-\gamma)}} = \frac{H^{\gamma}}{R_0} \Big|_{\gamma=1} = \frac{H}{R_0}$$
 (1)

On the other hand, the water volumetric flow into the barrel is constant and equal to Q. Now, making use of the facts that, from the cylindrical geometry, $dV/dt = \pi r^2 \cdot dH/dt$, and, from the mass-rate balance principle, $\rho \cdot dV/dt = \rho \cdot (Q_i - Q_o)$, the ODE describing the barrel problem is

$$\frac{dH}{dt} + \frac{H}{\tau_b} = \frac{Q_i}{\pi r^2} \qquad \left(\tau_b = R_0 . \pi r^2\right) \tag{2}$$

This ODE has $H = Q_i \cdot R_0 \cdot (1 - e^{-\frac{t}{T_b}})$ for solution (t > 0), from which the necessary condition for water to overflow is $Q_i > H_b/R_0$. But what barrels have to do with EEDs? Next section comes out to unveil this seeming mystery.

THE ANALYSIS OF THE EED THERMAL MODEL

By coating an electric resistance with a thick layer of high sensitivity explosive and applying an electric current to this circuit (bridgewire), the tiny explosive mass can certainly be initiated, but what is the best way to do that, by continuous or pulsed excitation? To answer this question, a simplified representation of the thermal phenomena involved in the EED ignition will be depicted.

Applying the energy-rate balance principle to the EED, the injected energy rate must be equal to the stored and the dissipated energy rates added together or, as in Eq. 3,

$$P_{i} = C_{T} \cdot \frac{d\theta}{dt} + \frac{\theta}{RT} \Rightarrow \frac{d\theta}{dt} + \frac{\theta}{\tau_{EE}} = \frac{P_{i}}{C_{T}}$$

$$(\tau_{EE} = R_{T} \cdot C_{T})$$
(3)

The electro-thermal model corresponding to this differential equation is given in Fig. 1 (for experimental procedures to determine $\tau_{EE} = R_t \cdot C_t$, see Rosenthal's (1961) and Prince and Leeuw's (1988)).

Hence, the EED temperature behaves exactly as the level of the fluid accumulated inside the barrel, since differential Eq. 2 and Eq. 3, which represent both phenomena, hydraulic and thermal, are analogous. As a matter of fact, this similarity will be very useful in grasping the subtleties of the heat transfer process involved in the EED ignition.

As it has already been shown,

$$\theta(t) = P_i R_T \cdot (1 - e^{-\frac{t}{\tau_{EE}}}) \tag{4}$$

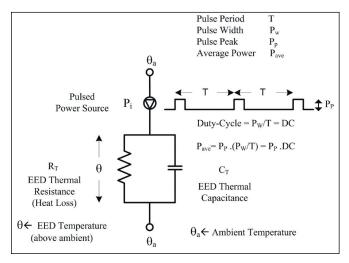


Figure 1. EED model.

Equation 4 is the solution of Eq.3, where P_i is constant. Therefore, the EED temperature is driven by the injected power.

From Eq.4, with $t\rightarrow\infty$, the maximum temperature (continuous input) is given by

$$\theta_{MAXCONT} = P_i \cdot R_T = P_{ave} \cdot R_T \tag{5}$$

Note how the EED temperature, due to the heat dissipation to the environment, via R_T , does not increase indefinitely – it is bounded (Fig. 2). Nevertheless, it suffices to make $\theta_{\text{MAXCONT}} > \theta_{\text{THRESHOLD}}$, by adjusting P_i , for ignition to occur.

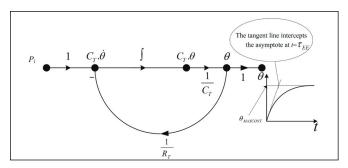


Figure 2. Signal flow graph (SFG) corresponding to Eq. 3 – the integrating effect of the thermal capacitance (C_T) is counterbalanced by the heat conduction to the surroundings $(1/R_T)$.

What happens when $P_i(t)$ is a train of power pulses (a switched power supply, for instance)? Despite the incontestable simplicity of the model adapted to our purposes, in this case, a certain mathematical expertise was required to solve it. For the complete solution of the EED ODE with a pulsed forcing function, the Laplace transform

method should be used (Wylie, 1975). Here, one is going to derive an approximated solution in the time domain.

From the theory of differential equations (Wylie, 1975), the total temperature can be factored into transient (the transient part is always negative and steadily approaches zero) and periodic components. However, after a large number of pulses (n >> 1, n is the pulse-cycle counting), the transient portion will have faded into insignificance (Fig. 3).

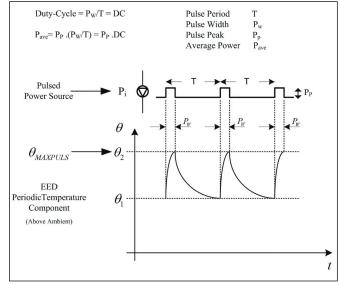


Figure 3. EED temperature after the settle down of the transient phase (pulsed excitation).

The problem was thus reduced to solve the following system of two ODEs with their associated boundary conditions (considering only the periodic component):

$$\begin{cases}
\frac{d\theta}{dt} + \frac{\theta}{\tau_{EE}} = \frac{P_P}{C_T}, & [0 \le t \le P_W] \land [\theta(0) = \theta_1, \ \theta(P_W) = \theta_2] \\
\frac{d\theta}{dt} + \frac{\theta}{\tau_{EE}} = 0, & [P_W \le t \le T] \land [\theta(P_W) = \theta_2, \ \theta(T) = \theta_1]
\end{cases}$$
(6)

From Eq. 6, it is not difficult to show that θ_1 and θ_2 must satisfy Eq. 7:

$$\begin{cases} \theta_{2} - \left(e^{-\frac{P_{W}}{TEE}}\right).\theta_{1} = P_{P}.R_{T}.\left(1 - e^{-\frac{P_{W}}{TEE}}\right) \\ \left(e^{\frac{(T - P_{w})}{TEE}}\right).\theta_{2} - \theta_{1} = 0; \end{cases}$$
 (7)

Solving Eq. 7 for $\theta_2 = \theta_{MAXPULS}$ (maximum temperature):

$$\theta_{MAXPULS} = \theta_2 = P_P.R_T. \left(\frac{1 - e^{-\frac{PW}{\tau_{EE}}}}{1 - e^{-\frac{T}{\tau_{EE}}}} \right)$$
(8)

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Equation 8, with $P_{ave} = P_p \cdot DC = P_p \cdot (P_w/T)$ fixed, becomes Eq. 9:

$$\theta_{MAXPULS} = \theta_{MAXCONT} \cdot \frac{1}{DC} \cdot \left(\frac{1 - e^{-\frac{T}{TEE}.DC}}{1 - e^{-\frac{T}{TEE}}} \right)$$
(9)

Since (see Fig. 1 and Fig. 3)

$$P_P = P_P \cdot \frac{\frac{P_W}{T}}{\frac{P_W}{T}} = \frac{P_P \cdot \frac{P_W}{T}}{\frac{P_W}{T}} = \frac{P_{ave}}{\frac{P_W}{T}} = \frac{P_{ave}}{DC},$$

$$\theta_{MAXCONT} = P_{ave} \cdot R_T$$
,

$$P_P \cdot R_T = \frac{P_{ave}}{DC} \cdot R_T = P_{ave} \cdot R_T \cdot \frac{1}{DC} = \theta_{MAXCONT} \cdot \frac{1}{DC}, and$$

$$\frac{P_W}{\tau_{EE}} = \frac{T}{\tau_{EE}} \cdot \frac{P_W}{T} = \frac{T}{\tau_{EE}} \cdot DC.$$

Now, defining the operational efficiency η (a ratio of two temperatures, a kind of temperature gain) as in Eq. 10,

$$\eta = \frac{\theta_{MAXPULS}}{\theta_{MAXCONT}} = \frac{1}{DC} \cdot \left(\frac{1 - e^{-\frac{T}{\tau_{EE}} \cdot DC}}{1 - e^{-\frac{T}{\tau_{EE}}}} \right), \tag{10}$$

it is evident that, for certain combinations of *DC* and T/τ_{EE} , η can be made >> 1 (Fig. 4).

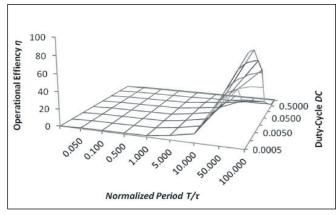


Figure 4. Operational efficiency (η) as a function of the duty-cycle (DC) and the normalized period $T/\tau_{_{FE}}$.

Apparently, the pulsed excitation of the EED can be much more efficient in terms of the maximum attainable temperature (this is true only if T is an independent variable, therefore under project control). In principle, for high efficiency, one just needs to operate the EED in the high T/τ_{EE} and low $DC=P_{_W}/T$ domains (or short pulse domain). These conditions are equivalent to $T >> \tau_{EE} >> P_{_W}$, since

$$\begin{cases} \left(\frac{T}{\tau_{EE}} >> 1\right) \Rightarrow \left(T >> \tau_{EE}\right) \\ \left(\frac{P_W}{T} << 1\right) \Rightarrow \left(\frac{P_W}{\tau_{EE}} \cdot \frac{\tau_{EE}}{T} << 1\right) \Rightarrow \left(\frac{P_W}{\tau_{EE}} << 1\right) \Rightarrow \left(\tau_{EE} >> P_W\right) \end{cases}$$

Considering that both $P_{ave} = P_p \cdot DC = P_p \cdot (P_w/T)$ and T are fixed, short pulses $(P_w \downarrow)$ also mean high peak-power $(P_p \uparrow)$. Therefore, this specific arrangement of T/τ_{EE} and DC makes the train of pulses function as a train of impulses. Then, the EED is quasi-instantaneously responding to the energy of each incoming pulse. One can see that as follows: from Eq. 8, with $T >> \tau_{EE} >> P_w$?

$$\theta_{MAXPUL_{S}} = P_{p} \cdot R_{T} \cdot \left(\frac{ \frac{\cong 1 - \frac{P_{w}}{T_{EE}}}{1 - e^{-\frac{P_{w}}{T_{EE}}}}}{1 - e^{-\frac{T}{T_{EE}}}} \right) \cong P_{P} \cdot R_{T} \cdot \left[\frac{1 - \left(1 - \frac{P_{w}}{T_{EE}}\right)}{1} \right]$$

$$\cong P_{p} \cdot R_{T} \cdot \frac{P_{w}}{T_{EE}}$$

$$\cong \frac{1}{C_{T}} \cdot \underbrace{\frac{P_{w}}{T_{EE}}}_{P_{P} \cdot P_{W}} \Rightarrow$$

$$(11)$$

 $\theta_{MAXPULS} \propto Pulse Energy$

This is exactly the case of electrostatic discharges (ESD), actuating as $P_i(t)$, whenever C_T is small and R_T is large, a narrow pulse of high energy, an impulse for all practical purposes, can cause a rapid squib temperature increase, since the EED will not be able to dissipate, through $1/R_T$, the energy delivered to it, and the feedback loop in Fig. 2 can be ignored (by rapidly discharging a huge amount of water into a barrel, the liquid reaches its top almost instantaneously, because the leak through the hole at its base is irrelevant).

Likewise, the operation of electrical capacitive discharge fuses, a particular case of the pulsed excitation (a pulsed excitation with $T\rightarrow\infty$, $P_P\rightarrow\infty$ and $P_W\rightarrow0$), is now clear: almost all the thermal energy transferred to the EED will be converted, in just a single pulse, into a temperature increase, that is,

$$d\theta \cong \frac{P_P}{C_T} \xrightarrow{\int} \int d\theta = \theta_{MAXPULSE} \cong \theta_{IMPULSE} \cong \frac{1}{CT} \cdot \int_0^{P_W} P_P dt = \frac{1}{CT} \cdot P_P \cdot P_W$$

$$\theta_{MAXPULSE} \cong \theta_{IMPULSE} \propto (P_P \cdot P_W) \Rightarrow$$

$$\theta_{MAXPULSE} \cong \theta_{IMPULSE} \propto Pulse \ Energy$$
(12)

Note that to calculate
$$\int_{\theta_1}^{\theta_2} d\theta = \theta_2 - \theta_1 = \theta_{MAXPULS}$$
, the

EED temperature θ_I (above ambient temperature), at the beginning of the power pulse, was assumed to be null (the EED was not able to stock-pile thermal energy during the previous cycles), a valid supposition, as $T >> \tau_{FE}$.

Once again, if $\theta_{MAXPULSE} > \theta_{THRESHOLD}$, ignition is assured (only one short high-energy pulse, one-shot trigger impluse, is sufficient to initiate the explosive charge).

Also, if
$$\tau_{EE} >> T > P_W$$
, then, from Eq. 6,

$$\frac{d\theta}{dt} + \frac{\theta}{\tau_{EE}} = d\theta + \underbrace{\frac{\theta}{\tau_{EE}}}_{negligible} dt = \frac{P_P}{C_T} dt \Rightarrow$$

$$d\theta \cong \frac{P_P}{C_T} dt \xrightarrow{\int} \Delta\theta \cong \frac{P_P}{C_T} \cdot \Delta t,$$

and the EED temperature increases progressively by, $\Delta\theta = (P_P/C_T) \cdot P_W$ whenever an electric pulse of peak power P_{P} (no further assumption on the peak power magnitude was necessary) and duration P_{w} is applied to it (between pulses, $d\theta \approx 0$, and the EED temperature, θ , remains approximately constant). After many pulses, therefore, relatively slowly, the temperature θ can certainly cross the ignition threshold, causing, without notice, the squib initiation. This adiabatic effect (or temperature stacking – the EED is storing thermal energy) is nothing else than a gradual accumulation of thermal energy, cycle after cycle. The EED has become, via C_{τ} , a good longterm temperature integrator (a large, in diameter, barrel with a very small role in its base can gradually hold water inside it, since $\tau_b = R_0 \cdot \pi r^2$). This is a very interesting, singular EED behavior, with many important applications in the aerospace industry, because high peak power is no longer required.

Finally, if τ_{EE} is very small ($\tau_{EE} \ll P_W$), the EED temperature practically follows the source of electrical power pulses $P_i(t)$, once

$$\frac{d\theta}{dt} + \frac{\theta}{\tau_{EE}} = \frac{P_i(t)}{C_T} \Rightarrow \frac{\theta}{\tau_{EE}} \cong \frac{P_i(t)}{C_T} \Rightarrow \theta \cong R_T \cdot P_i(t)$$
negligible dominant factor

Now, forcing $R_T \cdot P_P > \theta_{THRESHOLD}$, which will require high peak power P_P , ignition is assured (this corresponds to a barrel of small cross-section with a large hole in its base - the liquid level follows the input pattern).

CONCLUSIONS AND FURTHER RESEARCH

Under strict conditions, pulsed excitation of EEDs can be advantageous, provided τ_{FF} is known:

If $\tau_{EE} >> T > P_{W}$ (with T being an independent variable, therefore under project control), remember that temperature gain η can be even notable, but high peak power will be demanded (remember that P_{ave} is constant).

On the other hand, if $\tau_{EE} >> T$, EED temperature can softly reach the ignition threshold (either by friend or foe action), after several cycles, due to the gradual integration of the energy conveyed by each pulse, a kind of discrete electrothermal energy pumping - the temperature stacking effect. If time-to-ignition is not critical, any reasonable amount of peak power will do.

And, if $\tau_{EE} \ll P_{W}$, the EED temperature simply follows the source of electrical power pulses $P_{E}(t)$.

It is also possible to initiate EEDs after one single highenergy impulse (one-shot fuse operation), particularly when C_T is small, and R_T is large.

Certainly, for optimized operation, the electrical driving source shall match, in terms of either energy or power, EEDs distinguishing features.

Furthermore, EEDs shall be shielded from their environment (coded ignition commands shall always be the rule): each EED must have its own local driving circuit module, only the coded commands shall come from the outside, preventing their soft ignition by foe intervention.

Following this conservative line, a matter that indeed deserves further investigation is the EED (one without any kind of protection) sensitivity to electromagnetic radiation (radar-like pulse-modulated radio frequency). Although closely linked with the subject developed in this article, it does not come within its scope (Thompson, 1973).

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