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Surfaces of Constant Mean Curvature in Euclidean 3-space Orthogonal to a Plane along its Boundary

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ABSTRACT

We consider compact surfaces with constant nonzero mean curvature whose boundary is a convex planar Jordan curve. We prove that if such a surface is orthogonal to the plane of the boundary, then it is a hemisphere.

Key words: surfaces with boundary, constant mean curvature, elliptic partial differential equation.

Let M be a compact surface immersed in \mathbb{R}^3 with constant mean curvature H whose boundary $\partial M = \Gamma$ is a planar Jordan curve of length L . Let D be a planar region enclosed by Γ and let A be the area of D . Let us consider the cycle $M \cup D$ oriented in such a way that its orientation, along M , coincides with the one defined by the mean curvature vector. Let Y be a Killing vector field in \mathbb{R}^3 and n_D be a unitary vector field normal to D in the orientation of $M \cup D$. Let ν be the unitary co-normal vector field along $\partial M = \Gamma$ pointing inwards M . By the flux formula it is known that $|H| \leq \frac{L}{2A}$ where equality holds if and only if $\nu = n_D$. That is, if and only if ν is constant and orthogonal to D along Γ .

In this work we consider the case $|H| \leq \frac{L}{2A}$ and we show that, in the above conditions, if M is embedded and Γ is convex, then M is a hemisphere. Explicitly we prove that:

THEOREM 1. *Let M be a compact embedded surface in \mathbb{R}^3 with constant mean curvature $H \neq 0$ whose boundary ∂M is a Jordan curve Γ in a plane $\mathbb{P} \subset \mathbb{R}^3$. Suppose that Γ is convex and M is perpendicular to the plane \mathbb{P} along its boundary. Then M is a hemisphere of radius $\frac{1}{|H|}$.*

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This theorem generalizes a result obtained by Brito and Earp (Brito and Earp 1991). We succeed in discarding their assumption that ∂M should be a circle of radius $\frac{1}{|H|}$.

A sketch of the proof of the theorem is as follows.

First, under the hypothesis of the theorem, M must be totally contained in one of the halfplanes determined by \mathbb{P} (see (Brito et al. 1991), for example). Now let M^* be the reflection of M with respect to the plane \mathbb{P} . Since M is orthogonal to \mathbb{P} along Γ , we have that $\tilde{M} := M \cup M^*$ is a compact surface without boundary, embedded in \mathbb{R}^3 . Note that *a priori* \tilde{M} is only of class C^1 along Γ . We will prove that \tilde{M} is at least of class C^3 . In this way we are able to use a classical result due to Alexandrov (see (Hopf 1983), for example) in order to establish that \tilde{M} is a sphere and therefore M is a hemisphere.

The regularity of \tilde{M} along Γ is achieved by means of the theory of elliptic partial differential equations. Let p be any point in $\Gamma \subset \tilde{M}$ and Ω be an open neighborhood of 0 in $T_p \tilde{M}$ chosen in such a way that locally around p , \tilde{M} may be described as the graph of a function $u : \Omega \rightarrow \mathbb{R}$. For our purposes, it suffices to consider Ω of class $C^{1,1}$.

It is clear that $u \in C^1(\Omega)$. So, ∇u is well-defined and continuous. Since Ω is bounded we have that $u \in W^{1,2}(\Omega)$.

Let us denote the linear space of k -times weakly differentiable functions by $W^k(\Omega)$. For $p \geq 1$ and k a non-negative integer, we let $W^{k,p}(\Omega) = \{u \in W^k(\Omega), D^\sigma u \in L^p(\Omega) \text{ for all } |\sigma| \leq k\}$.

The Hölder spaces $C^{k,\alpha}(\Omega)$ are defined as the subspaces of $C^k(\Omega)$ consisting of functions whose k -th order partial derivatives are locally Hölder continuous with exponent α in Ω .

We define on Ω the following linear operators:

$$L_1 v := D_i(a^{ij} D_j v), \quad v \in W^{1,2}(\Omega) \quad i, j = 1, 2$$

and

$$L_2 v := A^{ij} D_{ij} v, \quad v \in W^{2,2}(\Omega) \quad i, j = 1, 2,$$

where the coefficients a^{ij} are given by

$$a^{11} = a^{22} = \frac{1}{1 + |\nabla u|^2}, \quad a^{12} = a^{21} = 0$$

and the coefficients A^{ij} are defined by $A^{11} = 1 + u_y^2$, $A^{12} = A^{21} = -u_x u_y$, $A^{22} = 1 + u_x^2$. Finally, the symbols D_i , D_{ij} , $i, j = 1, 2$ stand for partial differentiation.

We prove that u is a weak solution to the equation $L_1 u = 2H$. By the Corollary 8.36 (Gilbarg and Trudinger 1983) we have $u \in C^{1,\alpha}(\Omega)$. Moreover, by the Lebesgue's dominated convergence theorem and Lemma 7.24 (Gilbarg and Trudinger 1983) we can conclude that $u \in W^{2,p}(\Omega')$ for any subdomain $\Omega' \subset\subset \Omega$. Fixed $\Omega' \subset\subset \Omega$, we consider the equation

$$L_2 v = 2H (1 + |\nabla u|^2)^{\frac{3}{2}}. \quad (1)$$

We observe that $u \in W^{2,2}(\Omega')$. Thus, L_2u is well-defined. Moreover, we have that $L_2u = 2H(1 + |\nabla u|^2)^{\frac{3}{2}}$ in Ω' . It means that $u \in W^{2,2}(\Omega')$ is a solution to the equation (1) just above. Now using the Theorem 9.19 (Gilbarg and Trudinger 1983) we obtain $u \in C^{2,\alpha}(\Omega')$. Repeating the same procedure we conclude that $u \in C^\infty(\Omega')$. Thus, \tilde{M} is C^∞ . So, \tilde{M} is a regular compact closed surface embedded in \mathbb{R}^3 with constant mean curvature. By the Theorem 5.2 (Chapter V, (Hopf 1983)) we conclude that \tilde{M} is a (round) sphere and therefore M is a hemisphere.

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RESUMO

Consideramos superfícies compactas com curvatura média constante e não nula as quais têm como bordo uma curva de Jordan plana convexa. Provamos que, se uma tal superfície é ortogonal ao plano do bordo então é um hemisfério.

Palavras-chave: superfícies com bordo, curvatura média constante, equações diferenciais parciais elípticas.

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