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Conserved Sandpile with A Variable Height Restriction

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Abstract We study a restricted-height version of the one-dimensional Oslo sandpile with conserved density by using periodic boundary conditions. Each site has a limiting height which can be either two or three. When a site reaches its limiting height, it becomes active and may topple, loosing two particles, which move randomly to nearest-neighbor sites. After a site topples, it is randomly assigned a new limiting height. We study the model using mean-field theory and Monte Carlo simulation, focusing on the quasi-stationary state, in which the number of active sites fluctuates about a stationary value. Using finite-size scaling analysis, we determine the critical particle density and associated critical exponents.

Keywords SOC · Mean-field theory · Computer simulation

1 Introduction

Sandpile models are paradigmatic examples of self-organized criticality (SOC) [1, 2], a control mechanism that forces a system with an absorbing-state phase transition to its critical point [3–5], without explicit tuning

of control parameters [6]. SOC in a slowly driven sandpile corresponds to an absorbing-state phase transition in a model with the same local dynamics, but a fixed number of particles [3, 7–11], so-called *conserved sandpiles* [10, 12–14]. Absorbing-state phase transitions arise in the context of spatial stochastic models and correspond to a transition between an active, fluctuating phase, and an absorbing one, which allows no escape [24, 25, 27].

Sandpile models with probabilistic toppling rules, typified by the Manna model [15, 16], are commonly designated as *stochastic sandpiles*—this study has been central to establishing the connection between SOC and absorbing-state phase transitions. An important stochastic model is the Oslo model [17], inspired by experimental studies on rice piles. In this work, we study a conserved version of the Oslo model, characterizing its absorbing-state critical point.

An inconvenient feature of many sandpile models is the absence of an upper bound on the number of particles that may occupy a given site, which complicates theoretical approaches such as n -site approximations or continuum descriptions. This motivated the study on *restricted* sandpiles [18]. In the present work, we impose a height restriction on the conserved Oslo model. Since the symmetries and conserved quantities of the restricted and unrestricted models are the same, one expects, on the basis of experience with critical phenomena both in and out of equilibrium, that the models belong to the same universality class, as is indeed borne out for conserved versions of the Manna model [19–21]. The symmetries here are limited to spatial translation and inversion, while the conservation law is that of particle number. This universality class has come to be known as the conserved directed percolation (CDP) class. On this basis, it would be most surprising if the restricted Oslo model were to belong to a different universality class

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than its unrestricted counterpart. This question nevertheless merits investigation via numerical simulation. Recently, it was suggested that the critical behavior of conserved stochastic sandpiles, in fact, belongs to the (nonconserved) directed percolation class [22], but further studies are required to verify this assertion.

The remainder of this paper is organized as follows: In Section 2, we describe the model and in Section 3, develop a one-site mean-field approximation. Our numerical results are reported in Section 4, and we present our conclusions in Section 5.

2 Model

We study a restricted sandpile model with a variable height limit, defined on a lattice of $N_{\text{site}} = L^d$ sites, where d is the dimension of space. The configuration is specified by the particle numbers z_i ($i = 1, \dots, N_{\text{site}}$) at each site. Each site has a *critical height* $c_i \in \{2, 3\}$, with equal probability, such that $z_i \leq c_i$. A site with $z_i = c_i$ is said to be *active*. Any configuration devoid of active sites is *absorbing*, i.e., it admits no escape. The dynamics of the model proceeds via *toppling* of active sites; each active site has a rate of unity to topple. (We mean by a “rate of unity” that the time unit is chosen such that if there are currently N_A active sites, then the time increment associated with the next toppling is $1/N_A$.) In a continuous-time (sequential) dynamics, each active site has the same probability of being the next to topple. When a site, say i , topples, two particles are transferred from i to sites j and j' , nearest neighbors of i . The two sites are chosen at random, independently, from the set of nearest neighbors, and so are not necessarily distinct; we refer to this procedure as an *independent* toppling rule. Due to the height restriction, any particle transfer that would result in a target site j having $z_j > c_j$ is rejected. (This means that the configuration $z_i = c_i, \forall i$ is also absorbing, since no particles can be transferred. The particle densities of interest in this study, however, remain far below the density associated with this configuration.) When site i loses a particle or particles due to toppling, a new limiting height c_i is selected, equal to 2 or 3, each with probability $1/2$. Thus, the dynamics has three stochastic elements: (1) the choice of the next site to topple; (2) the choice of target sites j and j' for particle transfers; and (3) the choice of the new limiting height after a site topples.

In practice, the next site to topple is selected at random from a list of currently active sites, which must naturally be updated following each toppling event. The time increment associated with each toppling (whether particles are

transferred or not) is $\Delta t = 1/N_A$, with N_A the number of active sites immediately prior to the event.

3 Mean-Field Theory

The primary aim of the mean-field analysis is to obtain a preliminary idea of the phase diagram and (assuming the latter possesses a phase transition), an order of magnitude estimate of the critical point. We consider the simplest mean-field approach, known as the one-site approximation. At this level of approximation, there are seven possible states $(i|j)$ for a given site, where $i = 0, 1, \dots, j$ represents the occupation number and $j = 2, 3$ denotes the limiting height, with associated probabilities denoted by P_{ij} . Taking into account the conditions of normalization

$$\sum_{j=2}^3 \sum_{i=0}^j P_{ij} = 1, \quad (1)$$

and of fixed density,

$$\sum_{j=2}^3 \sum_{i=0}^j i P_{ij} = \zeta, \quad (2)$$

there are only five independent variables at this level.

		FROM:						
		(0 2)	(0 3)	(1 2)	(1 3)	(2 2)	(2 3)	(3 3)
TO:	(0 2)							
	(0 3)							
	(1 2)							
	(1 3)							
	(2 2)							
	(2 3)							
	(3 3)							

Fig. 1 Transitions between states of a single site. Transitions marked with an “x” are impossible, and those ones related to diagonal elements are irrelevant

We begin the analysis by listing the possible transitions between states $(i|j)$ in Fig. 1. Each transition (at a given site, called the *central site* in this discussion) requires a specific configuration at the central site and at one or both of its nearest neighbors and a certain redistribution of particles from the toppling site. (The local configuration and the choice of target sites, j and j' , in the particle redistribution are statistically independent events.) In the one-site approximation, joint probabilities involving two or more sites are factorized. Denoting a joint two-site probability by $P_{ij|kl}$, the one-site approximation uses the replacement $P_{ij|kl} \rightarrow P_{ij} P_{kl}$, and similarly for three-site probabilities.

To illustrate how the rates associated with these transitions are calculated, we discuss some examples. Consider first the transition $(0|2) \rightarrow (1|2)$. The initial configuration must be either $(02|22)$ or $(03|23)$, that is, the central site must be vacant, have $z_c = 2$, and have an active neighbor. When the latter topples, exactly one particle must migrate to the central site. On a hypercubic lattice in d dimensions, each site has $2d$ nearest neighbors. Since the probability of exactly one particle jumping to the central site is $2(1/2d)[1 - (1/2d)]$, the rate (per site) of transitions of the kind $(0|2) \rightarrow (1|2)$ is

$$2d \frac{2d-1}{2d^2} P_{02}(P_{22} + P_{33}), \quad (3)$$

where the factor $2d$ represents the number of nearest neighbors.

Consider next the transition $(2|2) \rightarrow (0|2)$, which can occur via two mutually exclusive paths. In one, both particles liberated when the central site topples attempt to migrate to the same neighbor, an event having a probability $1/4d^2$. In order for both particles to actually migrate, the difference $z_c - z$ at the target site must be greater than one. Thus, the initial configurations for which this transition may occur are $(00|23)$, $(02|32)$, and $(12|32)$. The transition rate for this path is

$$\frac{1}{2} 2d \frac{1}{4d^2} P_{22}(P_{02} + P_{03} + P_{13}), \quad (4)$$

where the factor $1/2$ represents the probability that the limiting height retains the value of 2 following the toppling event. In the other path, the two particles migrate to distinct neighbors of the central site. The configurations that allow this transition to occur are $(2^\dagger 22^\dagger|222)$, $(2^\dagger 23^\dagger|223)$, and $(3^\dagger 23^\dagger|323)$, where 2^\dagger and 3^\dagger denote, respectively, sites

with $z < 2$ and $z < 3$. Thus, the transition rate for this path is

$$\frac{2d-1}{4d} P_{22}(P_{2^\dagger 2} + P_{3^\dagger 3})^2. \quad (5)$$

Evaluating the rates of the remaining transitions, we find the equations that govern the probabilities $P_{i,j}$ at this level of approximation. The equations for the P_{ij} are

$$\begin{aligned} \frac{dP_{02}(t)}{dt} = & \frac{1}{4d} P_{22}(P_{02} + P_{03} + P_{13}) + \frac{2d-1}{4d} P_{22}(P_{2^\dagger 2} + P_{3^\dagger 3})^2 \\ & - \frac{4d-1}{2d} P_{02}(P_{22} + P_{33}), \end{aligned} \quad (6)$$

$$\begin{aligned} \frac{dP_{03}(t)}{dt} = & \frac{1}{4d} P_{22}(P_{02} + P_{03} + P_{13}) + \frac{2d-1}{4d} P_{22}(P_{2^\dagger 2} + P_{3^\dagger 3})^2 \\ & - \frac{4d-1}{2d} P_{03}(P_{22} + P_{33}), \end{aligned} \quad (7)$$

$$\begin{aligned} \frac{dP_{23}(t)}{dt} = & \frac{1}{2d} [P_{03} + 2(2d-1)P_{13} - (4d-1)P_{23}] \\ & (P_{22} + P_{33}) + \frac{1}{4d} [1 + 2(2d-1) \\ & \times (P_{22} + P_{33})] (P_{12} + P_{23}) P_{33}, \end{aligned} \quad (8)$$

$$\begin{aligned} \frac{dP_{12}(t)}{dt} = & \left(\frac{2d-1}{2d} P_{02} - \frac{4d-1}{2d} P_{12} \right) (P_{22} + P_{33}) \\ & + \frac{1}{4d} [1 + 2(2d-1)(P_{22} + P_{33})] P_{22}(P_{12} + P_{23}) \\ & + \frac{1}{4d} [P_{02} + P_{03} + P_{13} + (2d-1)(P_{2^\dagger 2} + P_{3^\dagger 3})^2] P_{33}, \end{aligned} \quad (9)$$

$$\begin{aligned} \frac{dP_{13}(t)}{dt} = & \left(\frac{2d-1}{2d} P_{03} - \frac{4d-1}{2d} P_{13} \right) (P_{22} + P_{33}) \\ & + \frac{1}{4d} [1 + 2(2d-1)(P_{22} + P_{33})] P_{22}(P_{12} + P_{23}) \\ & + \frac{1}{4d} [P_{02} + P_{03} + P_{13} + (2d-1)(P_{2^\dagger 2} + P_{3^\dagger 3})^2] P_{33}, \end{aligned} \quad (10)$$

$$\begin{aligned} \frac{dP_{22}(t)}{dt} = & \frac{1}{2d} [P_{02} + (4d-1)P_{12}] (P_{22} + P_{33}) \\ & + \frac{1}{4d} [1 + 2(2d-1)(P_{22} + P_{33})] P_{33}(P_{12} + P_{23}) \\ & - \frac{1}{2d} [P_{02} + P_{03} + P_{13} + (2d-1)(P_{2^\dagger 2} + P_{3^\dagger 3})^2] P_{22} \\ & + \frac{1}{2d} [1 + 2(2d-1)(P_{22} + P_{33})] P_{22}(P_{12} + P_{23}), \end{aligned} \quad (11)$$

$$\begin{aligned} \frac{dP_{33}(t)}{dt} = & \frac{1}{2d} [P_{13} + (4d-1)P_{23}] (P_{22} + P_{33}) \\ & - \frac{1}{2d} [P_{02} + P_{03} + P_{13}] P_{33} \\ & + \frac{2d-1}{2d} (P_{2^\dagger 2} + P_{3^\dagger 3})^2 P_{33} \\ & - \frac{1}{2d} [1 + 2(2d-1)(P_{22} + P_{33})] P_{33} \\ & \times (P_{12} + P_{23}). \end{aligned} \quad (12)$$

A solution of the above equations is performed numerically. We note that in light of the constraints expressed in Eqs. (1) and (2), we have only five independent equations. We also take advantage of the following symmetry: in the mean-field approximation, if $P_{02} = P_{03}$ initially, then this equality continues to hold throughout the evolution. A similar relation holds between $P_{12}(t)$ and $P_{13}(t)$. We, therefore, obtain a set of three independent differential equations for $P_{22}(t)$, $P_{23}(t)$ e $P_{33}(t)$, which are readily integrated using a fourth-order Runge–Kutta scheme [23]. We define the order parameter as the fraction of active sites,

$$\rho(t) = P_{22}(t) + P_{33}(t). \quad (13)$$

Numerical integration reveals that in one and two dimensions, $\rho(t) \rightarrow 0$ as $t \rightarrow \infty$ for particle densities $\zeta \leq 1$, while for higher densities, it attains a nonzero stationary value ρ_s (see Fig. 2), which grows continuously with $\zeta - 1$. Thus, in the one-site approximation, the model exhibits a continuous phase transition between an active and an absorbing state. Such a continuous absorbing-state phase transition is familiar from studies of the contact process [24] and of conserved stochastic sandpiles, among other models. We verify that for $\zeta \neq 1$, $\rho(t)$ approaches its stationary value exponentially: $|\rho(t) - \rho_s| \propto \exp(-t/\tau)$, where the relaxation time τ depends on ζ and diverges as $\zeta \rightarrow \zeta_c = 1$, following $\tau \sim 1/|\zeta - \zeta_c|$, as is typical for a mean-field analysis of absorbing-state phase transitions [25]. The one-site approximation yields the critical exponent β , defined via $\rho_s \sim (\zeta - \zeta_c)^\beta$, (for $\zeta > \zeta_c$), as $\beta = 1$ for both $d = 1$ and $d = 2$. This value is expected for mean-field analysis of continuous absorbing-state phase transitions in models that do not possess up-down (or particle-hole) symmetry [25]. The reason is that in the absence of such a symmetry, all powers of the order parameter are allowed in

the mean-field equations of motion, so that, near the critical point, the terms proportional to ρ and ρ^2 dominate (that is, $d\rho/dt \simeq a\rho - b\rho^2$, with $a \propto \zeta - \zeta_c$ and $b > 0$), and the stationary value of ρ is proportional to $\zeta - \zeta_c$.

4 Simulation

We simulate the restricted sandpile model described above in one dimension using periodic boundaries on rings of $L = 500, 1,000, 1,500$, and $2,000$ sites. The initial configuration is defined by assigning limiting heights $z_c = 2$ or 3 with equal probabilities, independently, to each site and then distributing randomly N particles among the L sites, avoiding occupancies that exceed the maximum height. The resulting *initial* distribution is statistically homogeneous; the occupations of different sites are essentially independent. Once all N particles have been inserted, the stochastic dynamics, with a fixed number of particles, begins. For each system size L , we study an interval of densities $\zeta = N/L$. In all cases, we use $N_r = 2,000$ independent realizations of the process. The maximum time is $t_m = 5 \times 10^4$ units for $L = 1,000$ and $t_m = 3 \times 10^5$ for $L = 2,000$.

To determine the critical behavior of the one-dimensional version of sandpile defined above, we study the time-dependent density of active sites $\rho(t)$ as well as their survival probability $P(t)$. Figure 3 shows the typical simulation behavior for $\rho(t)$ and $P(t)$. We see that $\rho(t)$ possesses a transient part before reaching a well-defined stationary value $\rho_s(\zeta, L)$, while the survival probability $P(t) \propto \exp(-t/\tau(\zeta, L))$ has an exponential decay. Discarding the initial transient portion of the data, the survival time $\tau(\zeta, L)$ is estimated by the slope of the curve.

In simulations, the particle density ζ cannot be varied continuously; for each system size L , it can only be changed in increments of $1/L$. To have access to intervals of particle density smaller than $1/L$, we follow a method employed in the study on conserved sandpile models [18] and pair contact process [26]. Initially, we determine the stationary average of ρ for a series of discrete values of the particle density, as shown in Fig. 4. Since it is reasonable to suppose that the resulting points fall on a smooth curve (as is indeed confirmed by the data), we then use quadratic interpolation to estimate ρ at particle densities that are not accessible for the sizes studied here.

By means of the analysis of these data, we obtain the order parameter and the mean survival time as functions of system size for diverse values of the particle density, as shown in Fig. 5. At an absorbing-state phase transition, the critical point of a phase transition is determined by seeking a power-law dependence of the order parameter ρ_s and the

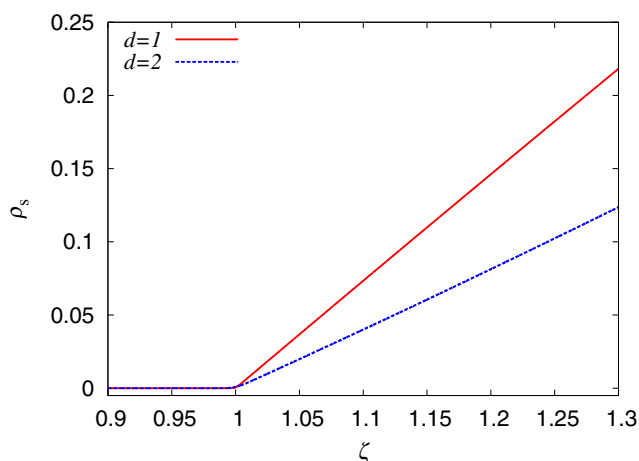


Fig. 2 (Colored online) Stationary order parameter ρ_s versus density ζ , in the one-site approximation, for $d = 1$ and $d = 2$

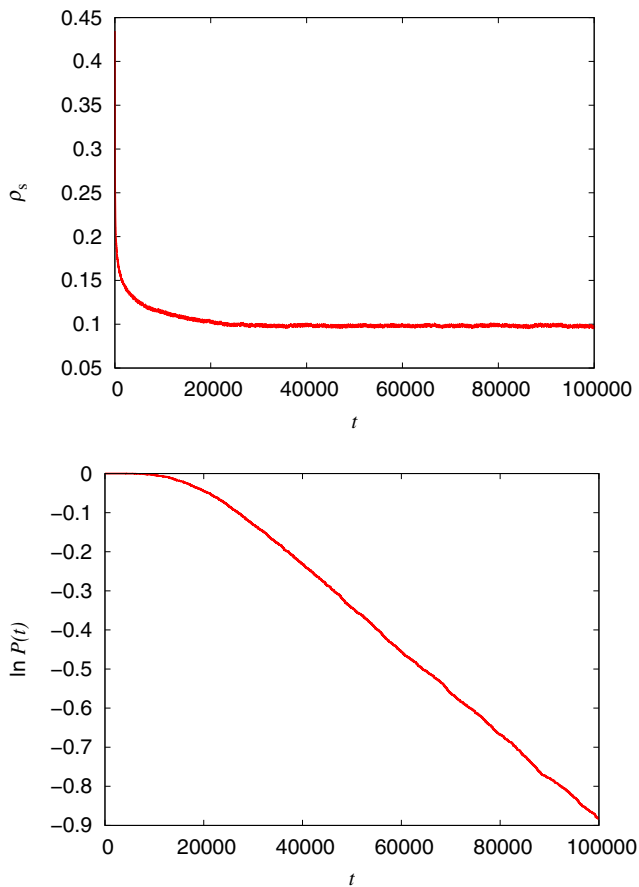


Fig. 3 (Colored online) Simulation: order parameter (upper panel) and survival probability (lower panel) versus time for $L = 1,000$ and particle density $\zeta = 1.64$

survival time τ on the system size L . These two parameters are governed by

$$\rho_s(\zeta, L) = L^{-\beta/\nu_\perp} \mathbf{C}(L^{1/\nu_\perp} \Delta), \quad (14)$$

$$\tau(\zeta, L) = L^{\nu_\parallel/\nu_\perp} \mathbf{R}(L^{1/\nu_\perp} \Delta), \quad (15)$$

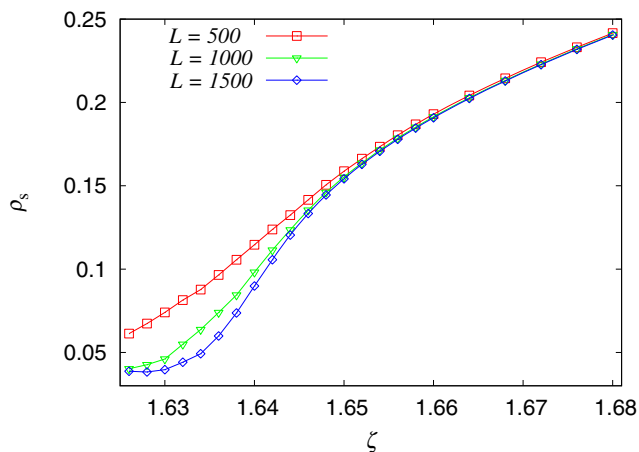


Fig. 4 (Colored online) Simulation: order parameter ρ_s versus particle density ζ for sizes as indicated

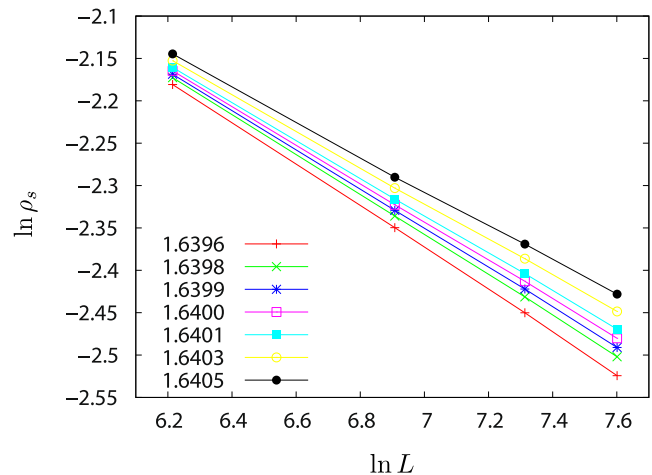


Fig. 5 (Colored online) Stationary order parameter ρ_s versus system size L for particle densities ζ as indicated

where $\Delta \equiv \zeta - \zeta_c$ is the distance from criticality and \mathbf{C} and \mathbf{R} are finite-size scaling relations [27]. At the critical point ($\Delta = 0$), we expect $\rho_s(\zeta_c, L) \sim L^{-\beta/\nu_\perp}$ and $\tau(\zeta_c, L) \sim L^{\nu_\parallel/\nu_\perp}$. With this in mind, we can estimate ζ_c and β/ν_\perp from the curve of $\rho_s(\zeta, L)$ that best approximates a straight line when plotted versus L on log scales.

This analysis yields $\zeta_c = 1.6400(2)$ and $\beta/\nu_\perp = 0.227(5)$, where the figures in parentheses denote the uncertainty in the last significant figure. Analyzing the data for the lifetime τ in the same manner, we obtain $z = \nu_\parallel/\nu_\perp = 1.44(3)$. (The uncertainties are related to two contributions: one due to the uncertainty of the fit and the other due to the uncertainty in the values of ρ_s and τ for each size L .) We estimate the critical exponent ν_\perp by plotting $L^{\beta/\nu_\perp} \rho_s(\zeta, L)$ versus $L^{1/\nu_\perp} \Delta$ for various system sizes, seeking the value of ν_\perp which yields the best data collapse. Figure 6 shows that a good collapse is obtained using $1/\nu_\perp = 0.704(5)$. The critical exponent β that relates the order parameter ρ_s with Δ

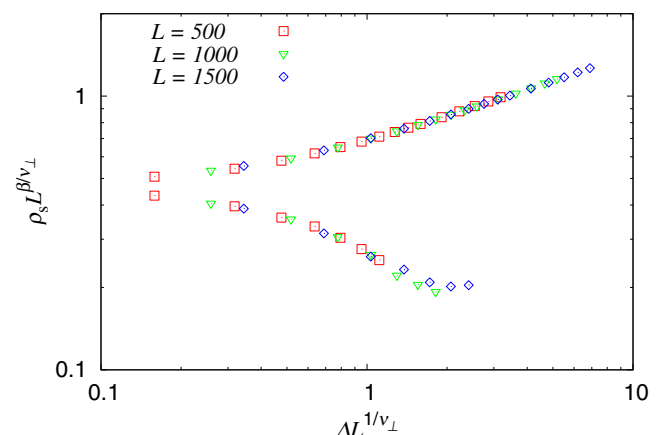


Fig. 6 (Colored online) Scaling plot for the density of active sites

Table 1 Critical exponents for one-dimensional models in the CDP universality class compared with estimates from the present work

Model	β/ν_{\perp}	z	β
Rest. Manna ^a	0.213(6)	1.55(3)	0.29(1)
CDP - FT ^b	0.214(8)	1.47(4)	0.28(2)
SRW ^c	0.212(6)	1.50(4)	0.290(4)
Present work	0.227(5)	1.44(3)	0.322(5)

^aRestricted Manna model [28]^bCDP field theory [29]^cSleepy random walkers [30]

through the relation $\rho_s = \Delta^{\beta}$ is then easily determined as $\beta = 0.322(5)$.

Table 1 compares our estimates for critical exponents with those obtained in studies on other one-dimensional models in the CDP universality class. Despite apparent differences, it is important to recall that previous studies have revealed that simulations of large systems (20,000 sites or larger) are needed to obtain reliable values of critical exponents for this class [28, 30]. For example, studies using smaller system sizes overestimated the value of the critical exponent β in the conserved Manna sandpile, in both its restricted and unrestricted versions [3, 18].

5 Conclusions

We study a height-restricted fixed-density version of the Oslo sandpile in one dimension. At each site, the limiting height z_c may be either 2 or 3. The model is found to exhibit a continuous phase transition between an active and an absorbing state at a critical value of the particle density, ζ_c . The one-site mean-field approximation predicts $\zeta_c = 1$, whereas simulations yield $\zeta_c = 1.6400(2)$. The small sizes analyzed here limit the reliability of our estimates for the critical exponents. Comparison with literature values (Table 1) raises the possibility that the restricted Oslo model does not belong to the conserved directed percolation class. More definitive conclusions will however require studies of larger systems.

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