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OPTIMIZATION OF ARSENITE ADSORPTION ON HYDROXY APATITE BASED ADSORBENT USING THE ADAPTIVE NEURO-FUZZY INFERENCE SYSTEM

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Abstract:

This paper describes an optimization procedure for the adsorption of arsenite ions from wastewater using the Adaptive Neuro-Fuzzy Inference System (ANFIS). The adsorbent is based on hydroxy apatite, a natural material obtained from carp (Cyprinus carpio) scales.

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The input parameters were the influence of pH, the temperature, the initial concentration and reaction time of arsenite adsorption while the adsorption capacity and the arsenite removal percentage were studied as the output parameters.

Key words: arsenite, adsorption, carp scales, hydroxy apatite, adsorbent, ANFIS.

Introduction

The Earth crust comprises 1.8 ppm of arsenic which is at the 55th place regarding its abundance. It can be mainly found in the following oxidation numbers: +1 (arsenide), 0, -3 (arsenite) and -5 (arsenate) (Järup, 2003), (Jovanović et al, 2011). As a metalloid, arsenic is not toxic but toxicity significantly changes depending on the oxidation number. Arsenite is the most toxic form of arsenic, followed by arsenate and then organic arsenide. Arsenic contamination is mainly a result of natural geothermal (volcanoes) and human activities. In nature, arsenic can be found in numerous oxide and hydroxide species in combination with different metal and nonmetal ions. Arsenic is used in the pesticide industry, wood industry, electronic industry and it comes as a byproduct of ore and metal smelting, etc. Arsenic poisoning leads to serious health problems, from skin irritation, respiratory and digestion problems to infertility, heart and immunity problems, DNA damage and cancer. It accumulates in the human body and with time leads to serious illnesses and death. Plants absorb arsenic easily, thus it efficiently enters the food chain (Veličković et al, 2016). The maximum allowable concentration of arsenic in drinking water is $10 \mu\text{g dm}^{-3}$ and the maximum concentrations of arsenic in wastewater discharged to the receiver must not exceed 0.1 mg dm^{-3} (WHO, 2016), (Dziubek, 2017).

Studies have shown that sediment and biological apatites have capability of heavy metal and radionuclide bonding in a way that adsorbed quantities are 106 times larger than their concentrations in the surrounding environment and the desorption does not occur up to billion years, not even during the change of pH values, temperature, chemical composition of the surroundings and tectonic changes (Nriagu, 1974), (Wright, 1990). Biological hydroxy apatites can easily bond ions but release them with great difficulty. The bonding process of different ions onto the structure of biological hydroxy apatites can be useful for living organisms (nontoxic concentrations of F, Cu, Mn, and Zn) or cause serious health disorders, especially to bones (Pb, Cd) (Iyengar &

Tandon, 1999). Mono, bi, tri, and tetravalent ions can be bound to apatites instead of calcium, phosphate or hydroxide ions.

Getting hydroxy apatite by chemical means is either complicated or environmentally unsafe (Nayak, 2010; Panda et al, 2014), so it is desirable to obtain it from natural sources, e.g. fish scales, fish scale hydroxy apatite - FSHAp (Chakraborty & RoyChowdhury, 2013), or animal bones (Lü et al, 2007; Luna-Zaragoza et al, 2009) which are otherwise considered as biowaste. The extraction of FSHAp from biowaste is economically and environmentally desirable because around 50% of total used fish mass ends up in waste, while 4% of that waste consists of fish scales (Kongsri et al, 2013), (Sukaimi et al, 2014). The idea of getting FSHAp from waste fish scale is investigated in numerous studies (Ferraz et al, 2004), (Nayak, 2010), (Catros et al, 2010), (Jadalannagari et al, 2011), (Ramli et al, 2011), (Sobczak-Kupiec & Wzorek, 2012), (Scalera et al, 2013), (Bajić et al, 2013). The potential of thus obtained FSHAp is significant, because annually between 18 and 30 million tons of fish scales appear as waste in the whole world (Huang et al, 2011); furthermore, its environmental and biological compatibility and nontoxicity should be taken into account. Numerous studies have shown that FSHAp has great properties as an adsorbent for the removal of heavy metal ions, anions and radionuclides from water due to its high value of adsorption capacity, insignificant water solubility, good availability, low cost and great stability in the presence of oxidation and reduction compounds (Kongsri et al, 2013). FSHAp has been confirmed as a good adsorbent of Pb, Zn, Co, Cd, As, Cu, Ni, Fe, Al, Se, Am, U, Pu, Tc, nitrate, sulfate, fluoride, carbonate and chloride ions (Ma et al, 1994a), (Ma et al, 1994b), (Xu et al, 1994), (Thomson et al, 2003), (Gómez del Río et al, 2004), (Corami et al, 2008), (Stötzel et al, 2009), (Dimović et al, 2009), (Islam et al, 2011), (Bajić et al, 2013).

In one study (Bajić et al, 2013), it has been presented that the adsorbent obtained from carp fish scales (CSHAp) has a great affinity to Cd(II), Pb(II) and As(V) ions. The paper shows that the aforementioned ions can be successfully removed from water for pH values between 6 and 8 and that the presence of interfering ions in water does not affect the adsorption process.

In this study, the biological apatite was obtained from the cycloid scales of freshwater fish carp (*Cyprinus carpio*) from the Ečka (Zrenjanin, Serbia) fish farm.

Adaptive neural networks (neuro-fuzzy networks) are based on unifying the concepts of fuzzy logic and artificial neural networks - theories that have already found their place at the top of the interest of

researchers in the field of artificial intelligence (Jang, 1991), (Jang, 1993), (Jang et al, 1997), (Abraham, 2005), (Tahmasebi, 2012). Using an input/output set, the Adaptive Neuro-Fuzzy Inference System (ANFIS) forms a fuzzy logic system in which the membership function parameters are created using a backpropagation algorithm or other algorithms such as genetic algorithms, simulated annealing algorithm, bee algorithm, etc. It is based on the so-called Takagi-Sugeno system. This approach allows the fuzzy system to learn from the data it is modeling (Takagi & Sugeno, 1985), (Mehran, 2008), (Pamučar et al, 2018), (Sremac et al, 2018).

The ANFIS was used in this study to evaluate the effects of four influencing variables (i.e. pH, temperature, initial concentration of adsorbate, and adsorption time) on the removal efficiency of arsenite ions on carp scales.

Experimental part

Materials

Fish scales were extracted from the farmed carp (*Cyprinus carpio*), grown in the Ečka fish farm. The scales were sonicated in a 5% solution of hydrogen peroxide and triple rinsed with deionized (DI) water and dried. The pure dried carp scales were ground. Adsorbents were prepared from the analytical-grade arsenite standard NaAsO_2 (Sigma-Aldrich). A stock solution containing 1000 mg dm^{-3} was prepared, and additionally diluted with DI water to the required ionic concentrations for the adsorption experiments.

Adsorption experiments

The arsenite adsorption capacities of CSHAp were determined in a batch reactor. The batch adsorption experiments were performed using 100 cm^3 vial with addition of 0.5 mg of ground carp scales and 100 cm^3 ($m/V = 5 \text{ mg dm}^{-3}$) of As(III) solution of the initial concentrations of (C_0) $0.1, 0.2, 0.5, 1, 2, 5$ and 10 mg dm^{-3} . The bottles were placed in an ultrasonic bath. In order to evaluate the effect of pH on adsorption, the initial pH values of the solutions were set at $2.0, 4.0, 6.0, 8.0$ and 10.0 by adjusting them with 0.01 and 0.1 mol dm^{-3} NaOH, and 0.01 and 0.1 mol dm^{-3} HNO_3 . The experiments were conducted at three temperatures: $20, 30$ and $40 \text{ }^\circ\text{C}$. The time-dependent adsorbate concentration changes were examined in the range of $5\text{--}120$ minutes. After sonication, the mixtures of adsorbent and ionic solutions were filtered through a $0.2 \text{ }\mu\text{m}$ PTFE membrane filter, acidified and analyzed. Adsorption experiments were conducted in a batch system under ultrasonic stirring. The

ultrasonic bath (Bandelin Electronic, Berlin, Germany, power 80 and 120 W, frequency 35 kHz) was thermostated by circulating water through the jacket.

The arsenite concentrations in the solutions before and after the adsorption were analyzed by inductively coupled plasma mass spectrometry (ICP-MS), using an Agilent 7500ce ICP-MS system (Waldbronn, Germany) equipped with an octopole collision/reaction cell, Agilent 7500 ICP-MS ChemStation software, a MicroMist nebulizer and a Peltier cooled (2.0 °C) quartz Scott-type double pass spray chamber. The standard optimization procedures and criteria specified in the manufacturer's manual were followed. The ICP-MS detection limit was 0.030 µg dm⁻³ and the relative standard deviation of all arsenic species investigated was between 1.3 and 5.1 %.

The maximum adsorption capacity has been achieved at pH = 4, C₀ = 10 mol dm⁻³, T = 40 °C and t = 60 min and the maximum percentage of arsenite removal has been achieved at pH = 4, C₀ = 0.1 mol dm⁻³, T = 40 °C and t = 60 min, as it can be seen from Table 4.

ANFIS setup

The ANFIS method is used to examine the possibility of modeling and the prediction of As(III) adsorption on CSHAp. The input variables of the fuzzy logic system (FLS) are the initial adsorbate concentration (X₁), the pH value of the solution (X₂), the adsorption temperature (X₃) and the adsorption time (X₄). Along with the four input variables, the FLS has two output variables: the adsorption capacity (Y₁) and the adsorbate removal percentage (Y₂). The intervals of the input and output FLS variables are given in Table 1.

Table 1 – Intervals of the input and output FLS variables
Таблица 1 – Интервалы входных и выходных переменных системы нечеткой логики

Табела 1 – Интервали улазних и излазних променљивих ФЛС-а

Variable	Interval	Unit
X ₁	[0.1, 10]	mg dm ⁻³
X ₂	[2, 10]	-
X ₃	[20, 40]	°C
X ₄	[5, 120]	min
Y ₁	[0.92, 24.5]	mg g ⁻¹
Y ₂	[2.34, 95.0]	%

The coefficient weights of the input FLS variables are determined using the DEMATEL method (Pamučar et al, 2014) and the manner of

their influence on the adsorption capacity, q , and the percentage of adsorbate removal, R , is given in Table 2.

Table 2 – Weights of the input FLS variables and their influence on the output variables
Таблица 2 – Веса входных переменных системы нечеткой логики и их влияние на выходные переменные
Табела 2 – Тежински коефицијенти улазних променљивих ФЛС-а и њихов утицај на излазне променљиве

Variable	Weight	Interval group			Influence on q	Influence on R
		a	b	c		
X_1	0.1903	0.1-0.5	0.5-2.0	2.0-10.0	Increase-increase	Increase-decrease
X_2	0.2169	2.0-4.0	4.0-6.0	6.0-10.0	Increase towards b, to others decrease	
X_3	0.2441	20-25	25-35	35-40	Increase-increase	Increase-increase
X_4	0.3487	5.0-45	45-90	90-120	Sharp increase to b, then mild increase	

Results and discussion

The Gauss membership functions (GMFs) are used for the description of the input FLS variables. The GMFs (Table 3) are selected because of the following benefits: they are easy to manipulate with when setting the FLS, the description of the input variables is quite acceptable, they ensure a satisfactory system sensitivity and provide the smallest error at the exit from the ANFIS model. Starting from the above assumptions, it is defined that each input variable has four membership functions (MFs) while the output variables (Y_1 and Y_2) are described with eight MFs. The parameters of the MFs for the input variables before the ANFIS training are presented in Table 3.

The initial FLS testing was performed after the parameters of the input/output variables and the base of the rules had been defined. It was observed that the system had not yielded satisfactory results in relation to the FLS output data and the desired set of solutions. The difference between the expected results and the value of the output criterion function was not within the limits of tolerance. Attempting to change the type and parameters of the membership functions at the exit in order to obtain satisfactory values did not give the expected results. Table 4 shows the experimentally determined output values based on a set of input parameters, that is, the results of 29 experiments for the adsorption of As(III) on CSHAp.

Table 3 – Parameters of the membership functions before the ANFIS training
 Таблица 3 – Параметры функций членства перед обучением ANFIS
 Табела 3 – Параметри функција припадности пре обучавања АНФИС

X_1	MF 1	MF 2
	$\mu_{MF1}(X_1) = e^{-\frac{1}{2}\left(\frac{x-0.519}{1.75}\right)^2}$	$\mu_{MF2}(X_1) = e^{-\frac{1}{2}\left(\frac{x-4.238}{1.813}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_1) = e^{-\frac{1}{2}\left(\frac{x-6.99}{1.659}\right)^2}$	$\mu_{MF4}(X_1) = e^{-\frac{1}{2}\left(\frac{x-8.555}{1.542}\right)^2}$
X_2	MF 1	MF 2
	$\mu_{MF1}(X_2) = e^{-\frac{1}{2}\left(\frac{x-2.656}{0.9078}\right)^2}$	$\mu_{MF2}(X_2) = e^{-\frac{1}{2}\left(\frac{x-5.24}{0.9421}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_2) = e^{-\frac{1}{2}\left(\frac{x-7.336}{1.791}\right)^2}$	$\mu_{MF4}(X_2) = e^{-\frac{1}{2}\left(\frac{x-8.392}{1.465}\right)^2}$
X_3	MF 1	MF 2
	$\mu_{MF1}(X_3) = e^{-\frac{1}{2}\left(\frac{x-23.7}{3.44}\right)^2}$	$\mu_{MF2}(X_3) = e^{-\frac{1}{2}\left(\frac{x-26.67}{2.832}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_3) = e^{-\frac{1}{2}\left(\frac{x-30.96}{2.36}\right)^2}$	$\mu_{MF4}(X_3) = e^{-\frac{1}{2}\left(\frac{x-37}{4.06}\right)^2}$
X_4	MF 1	MF 2
	$\mu_{MF1}(X_4) = e^{-\frac{1}{2}\left(\frac{x-22.36}{14.84}\right)^2}$	$\mu_{MF2}(X_4) = e^{-\frac{1}{2}\left(\frac{x-43.3}{12.82}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_4) = e^{-\frac{1}{2}\left(\frac{x-73.15}{16.33}\right)^2}$	$\mu_{MF4}(X_4) = e^{-\frac{1}{2}\left(\frac{x-111.5}{19.52}\right)^2}$

Table 4 – Results of 29 experiments for the adsorption of arsenite on CSHAp
 Таблица 4 – Результаты 29 экспериментов по адсорбции арсенита на CSHAp
 Табела 4 – Резултати 29 експеримената за адсорпцију арсенита на CSHAp

X_1	X_2	X_3	X_4	q	R
0.50	4.00	20.00	5.00	1.60	32.00
0.50	4.00	20.00	10.00	2.50	50.00
0.50	4.00	20.00	15.00	3.20	64.00
0.50	4.00	20.00	30.00	3.69	73.80
0.50	4.00	20.00	45.00	4.16	83.20
0.50	4.00	20.00	60.00	4.22	84.40
0.50	4.00	20.00	120.00	4.20	84.00
0.10	4.00	40.00	60.00	0.95	95.00
0.20	4.00	40.00	60.00	1.82	91.00
0.50	4.00	40.00	60.00	4.29	85.80
1.00	4.00	40.00	60.00	8.02	80.20
2.00	4.00	40.00	60.00	15.20	76.00
5.00	4.00	40.00	60.00	17.60	35.20
10.00	4.00	40.00	60.00	24.50	24.50
5.00	2.00	30.00	60.00	16.40	32.80
5.00	4.00	30.00	60.00	21.20	42.40
5.00	6.00	30.00	60.00	18.50	37.00
5.00	8.00	30.00	60.00	6.32	12.60
5.00	10.00	30.00	60.00	1.17	2.34
0.10	4.00	20.00	60.00	0.92	92.00
0.20	4.00	20.00	60.00	1.78	89.00
0.50	4.00	20.00	60.00	4.22	84.40
1.00	4.00	20.00	60.00	7.87	78.70
2.00	4.00	20.00	60.00	14.32	71.60
5.00	4.00	20.00	60.00	15.90	31.80
10.00	4.00	20.00	60.00	16.50	16.50
10.00	2.00	30.00	30.00	12.30	12.30
10.00	4.00	30.00	30.00	17.40	17.40
10.00	6.00	30.00	30.00	8.75	8.75

An analysis of the obtained data at the FLS output yielded an average error of 8.371. In addition to a relatively high error, the FLS for some values of the input parameters was overly sensitive, while for some values it was insufficiently sensitive. Figure 1 presents a set of the FLS output values, i.e. a scenario describing the system's response for individual input values. The plane surfaces (plateaus) represent the places where the FLS is inert for the input parameter values, while the steep sections represent the values of the input parameters for which the FLS is too sensitive. An attempt to reduce the output error and improve

the sensitivity of the FLS by correcting the base of the rules and changing the parameters of the MF did not yield the expected results. Because of this, the transformation of the FLS into the ANFIS was performed (Figure 1).

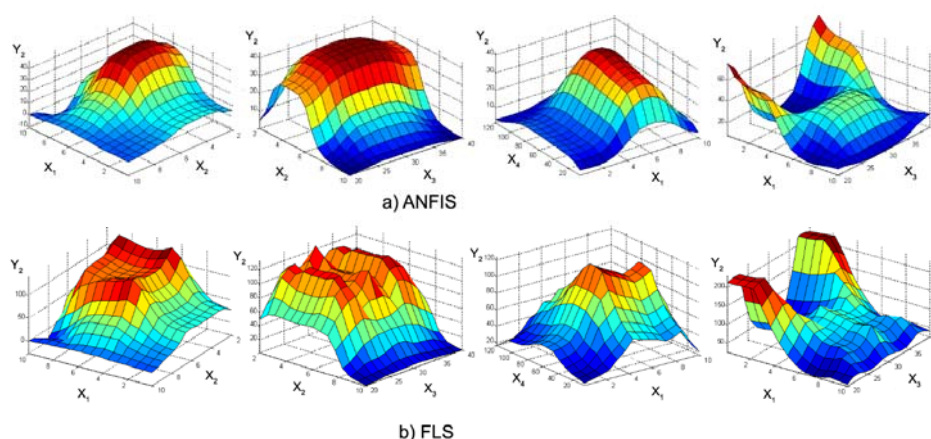


Figure 1 – ANFIS (a) and FLS (b) output
 Рус. 1 – ANFIS (а) и FLS (б) выход
 Слика 1 – ANFIS (а) и FLS (б) излаз

The ANFIS has been trained for 4 epochs. In the training process, the MF of the initial FLS was set up, in order to reduce the error at the exit. In this study, a backpropagation algorithm was used for the ANFIS training. In the initial phase of the ANFIS training, in addition to the backpropagation algorithm, the simulated annealing algorithm and the hybrid algorithm were also tested (Dreiseitl & Ohno-Machado, 2002), (Pamučar et al, 2018), (Sremac et al, 2018). However, during the testing, a model that was trained with the backpropagation algorithm had a smaller error compared to other tested models.

The backpropagation algorithm calculates the error recursively (it performs a square error taking into account the output functions of each of the nodes of the network), starting from the output layer and going back to the input layer. By training a neural network with numerical examples, the initial MF forms are adapted. If there is a difference between the obtained and the expected data, modifications are made on the links between the neurons in order to reduce the error, i.e. the MFs in

the adaptive nodes are being adjusted. Table 5 shows the parameters of the ANFIS membership functions after training.

Table 5 – Parameters of the membership functions after the ANFIS training
Таблица 5 – Параметры функций принадлежности после обучения ANFIS
Табела 5 – Параметри функција припадности после обучавања ANFIS

X_1	MF 1	MF 2
	$\mu_{MF1}(X_1) = e^{-\frac{1}{2}\left(\frac{x-0.02895}{2.652}\right)^2}$	$\mu_{MF2}(X_1) = e^{-\frac{1}{2}\left(\frac{x-2.57}{1.915}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_1) = e^{-\frac{1}{2}\left(\frac{x-7.818}{1.783}\right)^2}$	$\mu_{MF4}(X_1) = e^{-\frac{1}{2}\left(\frac{x-10.05}{1.659}\right)^2}$
X_2	MF 1	MF 2
	$\mu_{MF1}(X_2) = e^{-\frac{1}{2}\left(\frac{x-2.118}{1.218}\right)^2}$	$\mu_{MF2}(X_2) = e^{-\frac{1}{2}\left(\frac{x-5.065}{1.229}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_2) = e^{-\frac{1}{2}\left(\frac{x-7.3}{0.8546}\right)^2}$	$\mu_{MF4}(X_2) = e^{-\frac{1}{2}\left(\frac{x-9.963}{1.184}\right)^2}$
X_3	MF 1	MF 2
	$\mu_{MF1}(X_3) = e^{-\frac{1}{2}\left(\frac{x-22.91}{2.83}\right)^2}$	$\mu_{MF2}(X_3) = e^{-\frac{1}{2}\left(\frac{x-26.15}{3.449}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_3) = e^{-\frac{1}{2}\left(\frac{x-34.69}{3.738}\right)^2}$	$\mu_{MF4}(X_3) = e^{-\frac{1}{2}\left(\frac{x-40}{2.831}\right)^2}$
X_4	MF 1	MF 2
	$\mu_{MF1}(X_4) = e^{-\frac{1}{2}\left(\frac{x-4.974}{16.28}\right)^2}$	$\mu_{MF2}(X_4) = e^{-\frac{1}{2}\left(\frac{x-41.47}{16.34}\right)^2}$
	MF 3	MF 4
	$\mu_{MF3}(X_4) = e^{-\frac{1}{2}\left(\frac{x-81.7}{16.12}\right)^2}$	$\mu_{MF4}(X_4) = e^{-\frac{1}{2}\left(\frac{x-120}{16.28}\right)^2}$

After the completion of 4 training epochs and the reduction of the average relative error to a value of 0.4830 and 0.6867 for q and R , respectively, it was concluded that the error is acceptable. Figure 2 graphically depicts the overlap of the ANFIS results with the experimental

data. In addition, the conclusion is that the neuro-fuzzy network is trained and able to generalize new input data for which it is not trained.

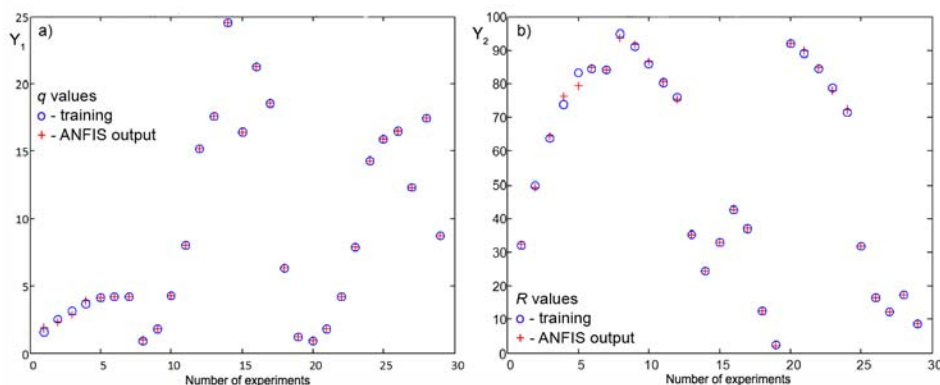


Figure 2 – Comparison of the ANFIS and the experimental data for q (a) and R (b)

Рис. 2 – Сравнение ANFIS и экспериментальных данных q (a) и R (b)

Слика 2 – Поређење резултата ANFIS са експерименталним резултатима за q (a) и R (b)

The data analysis was conducted using Marquardt's percent standard deviation (MPSD); Hybrid fractional error function (HYBRID); Average relative error (ARE); Average relative standard error (ARS); Sum squares error (ERRSQ/SSE); Normalized standard deviation (NSD); Standard deviation of relative errors (s_{RE}); Spearman's correlation coefficient (r_s); Non-linear chi-square test (χ^2), and Coefficient of determination (R^2) (Bajić et al, 2016). The errors for four trainings for the calculated output variables q and R are given in Tables 6 and 7.

Table 6 – Errors for four ANFIS training sets for the variable q

Таблица 6 – Ошибки в четырех этапах обучения ANFIS по переменной q

Табела 6 – Грешке за четири обуке ANFIS за променљиву q

Error functions	training 1	training 2	training 3	training 4
MPSD	231.4	148.9	82.83	4.447
HYBRID	739.0	315.0	112.2	0.4108
ARE	128.4	84.48	51.22	0.4830
ARS	2.187	1.407	0.7827	0.04202
ERRSQ	502.5	236.2	104.6	0.2395
NSD	218.7	140.7	78.27	4.202
s_{RE}	126.7	83.22	50.27	1.476
r_s	0.9779	0.9896	0.9954	0.9999
χ^2	0.004215	0.4081	0.9815	1
R^2	0.9658	0.9841	0.9907	0.9998

Table 7 – Errors for four ANFIS training sets for the variable R
 Таблица 7 – Ошибки в четырех этапах обучения ANFIS
 по переменной R

Табела 7 – Грешке за четири обуке ANFIS за променљиву R

Error functions	training 1	training 2	training 3	training 4
MPSD	10.77	6.810	3.802	1.338
HYBRID	39.00	18.74	6.764	1.414
ARE	5.363	2.232	1.580	0.6867
ARS	0.1018	0.06435	0.03592	0.01264
ERRSQ	452.4	213.1	91.07	28.39
NSD	10.18	6.435	3.592	1.264
SRE	4.404	2.725	1.679	0.8721
r_s	0.9801	0.9906	0.9960	0.9988
χ^2	0.9998	1	1	1
R^2	0.9832	0.9921	0.9963	0.9989

By analyzing the errors for four trainings and for the calculated output variables q and R given in Tables 6 and 7, it can be concluded that after the fourth training a significant error reduction has been achieved, which is especially expressed for the parameter q .

Conclusion

This paper shows the successful use of the ANFIS for the optimization procedure of the adsorption process of arsenite ions on carp scale hydroxy apatite adsorbent. It was found that the optimal conditions for the arsenite ions removal were as follows: $C_0 = 3.9 \text{ mg g}^{-1}$, $\text{pH} = 4.2$, $T = 40 \text{ }^\circ\text{C}$, and $t = 60 \text{ min}$. Only four training epochs have managed to reduce the errors and to predict the output values in a reasonably good manner. The implementation of the backpropagation training algorithm to the proposed model improved the quality of the generated appropriate fuzzy if-then rules to describe the input-output behavior of the adsorption system. The ANFIS method can, therefore, be applied to predict these and other output parameters of the adsorption process, which contributes to reducing the future number of experiments required to investigate the adsorption process. Also, the presented method can be applied to real water samples contaminated with arsenite ions.

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ОПТИМИЗАЦИЯ АДСОРБЦИИ АРСЕНИТА НА АДСОРБЕНТЕ ГИДРОКСИАПАТИТА С ИСПОЛЬЗОВАНИЕМ АДАПТИВНОЙ НЕЙРО-НЕЧЕТКОЙ ИНФЕРЕНЦИОННОЙ СИСТЕМЫ

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РУБРИКА ГРНТИ: 61.01.94 Охрана окружающей среды,
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ВИД СТАТЬИ: оригинальная научная статья

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Резюме:

В данной статье описана процедура оптимизации адсорбции ионов арсенита из сточных вод с использованием адаптивной нейро-нечеткой логической системы (ANFIS). В основе адсорбента лежит природный гидроксипатитный материал, полученный из чешуи карпа (Сyprinus carpio). В качестве параметров ввода использовались влияние pH, температуры, начальной концентрации и времени реакции на адсорбцию арсенита, а в качестве выходных параметров были исследованы адсорбционная емкость и процент удаления арсенита.

Ключевые слова: арсенит, адсорбция, чешуя карпа, гидроксипатитный адсорбент, ANFIS.

ОПТИМИЗАЦИЈА АДСОРПЦИЈЕ АРСЕНИТА НА АДСОРБЕНТ НА БАЗИ ХИДРОКСИАПАТИТА КОРИШЋЕЊЕМ АДАПТИВНОГ НЕУРО-ФАЗИ СИСТЕМА

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ОБЛАСТ: заштита животне средине, хемијско инжењерство

ВРСТА ЧЛАНКА: оригинални научни рад

ЈЕЗИК ЧЛАНКА: енглески

Сажетак:

У раду се описује поступак оптимизације адсорпције арсенитних јона из отпадних вода коришћењем адаптивног неуро-фази система (ANFIS). У основи адсорбента налази се природни

хидрокси-апатитни материјал добијен из крљушти шарана (Сурпинус сарпио). Као улазни параметри коришћени су утицај рН, температуре, почетне концентрације и времена адсорпције арсенита, а као излазни параметри испитивани су адсорпциони капацитет и проценат уклањања арсенита.

Кључне речи: арсенит, адсорпција, крљушт шарана, хидрокси-апатит, адсорбент, ANFIS.

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